

Abstractions

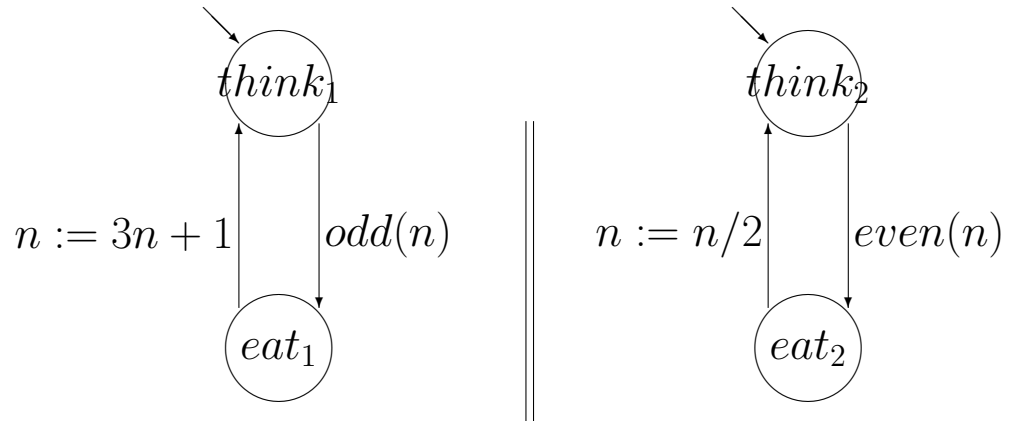
- State-spaces often get very large, with many variables
- Often, many of the variables are irrelevant for the analysis to be performed,
- or only some particular property of the variable is relevant.
- **Idea:** Create a simpler model, which “abstracts away” the irrelevant detail in the original model.
- Ideally, the “abstracting away” should be performed automatically, by a “compiler”.
- The abstract model can be analyzed by a model-checker.

Example:

Action System *Dining Mathematicians*

declare n : integer

initially $n \geq 1$



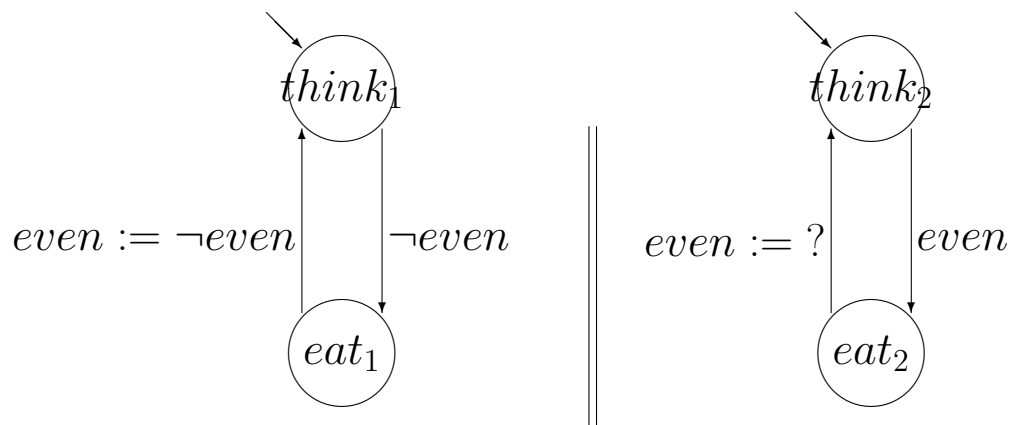
end

If we are only interested in control:

Action System *Abstract Mathematicians*

declare $even$: boolean

initially



end

How to relate the abstract to the more detailed?

- Let $\langle S, S^0, \rightarrow \rangle$ be the detailed transition system,
Let $\langle T, T^0, \rightarrow \rangle$ be the abstract transition system,
- **Idea:** Each abstract state represents a set of concrete states.
- **Formally:** This is represented by a *concretization function* $\gamma : T \mapsto \mathcal{P}(S)$, which maps each abstract state to a set of “concrete” states.
- We also want to “compute” on the set of abstract values. E.g., we want to take “union”, “intersection”, and so on.
- Define an ordering \sqsubseteq on abstract states by

$$t_1 \sqsubseteq t_2 \quad \equiv \quad \gamma(t_1) \subseteq \gamma(t_2)$$

- For each set $F \subseteq S$, define a “best approximation” $\alpha(F) \in T$, such that

$$\begin{aligned} \alpha(\gamma(t)) &= t && \text{for each } t \in T \\ \gamma(\alpha(F)) &\supseteq F && \text{for each } F \subseteq S \end{aligned}$$

We say that (α, γ) forms a *Galois Insertion* from $(\mathcal{P}(S), \subseteq)$ to (T, \sqsubseteq) .

Approximating the Transition Relation

- The relation \rightarrow is a *safe abstraction* of the relation \rightarrow between concrete states if

whenever $s \in \gamma(t)$ and $s \rightarrow s'$

there is t' such that $s' \in \gamma(t')$ and $t \rightarrow t'$

- We say that $\langle T, T^0, \rightarrow \rangle$ is a safe abstraction of $\langle S, S^0, \rightarrow \rangle$ if
 - \rightarrow is a safe abstraction of \rightarrow , and
 - $\forall s^0 \in S^0. \exists t^0 \in T^0. s^0 \in \gamma t^0$
- **Theorem:** If $\langle T, T^0, \rightarrow \rangle$ is a safe abstraction of $\langle S, S^0, \rightarrow \rangle$, then for each computation

$s^0 \ s^1 \ s^2 \ s^3 \ s^4 \ s^5 \ \dots$

of $\langle S, S^0, \rightarrow \rangle$, there is a computation

$t^0 \ t^1 \ t^2 \ t^3 \ t^4 \ t^5 \ \dots$

of $\langle T, T^0, \rightarrow \rangle$ such that

$s_i \in \gamma(t_i)$

for each i .

Relating Concrete and Abstract Behaviors and their Properties

For a system, and a temporal property ϕ , we want

$$\langle T, T^0, \rightarrow \rangle \models \phi \quad \text{implies} \quad \langle S, S^0, \rightarrow \rangle \models \phi$$

This can work, if we define

- For “simple” state formulas p :

$$t \models p \quad \text{iff} \quad \forall s \in \gamma(t). s \models p$$

Note that “the law of excluded middle” need not hold!

- Extend the above definition to properties of behaviors in the natural way.
- **Theorem:**

$$\langle T, T^0, \rightarrow \rangle \models \phi \quad \text{implies} \quad \langle S, S^0, \rightarrow \rangle \models \phi$$

Induced Operations and Transitions

Often, we want to compute an abstraction directly, based on the syntax.

- Assume that the original model has a set of actions (e.g., corresponding to “basic statements”)
- Assume that states are approximated in an abstract domain, as before:
- Approximate each action \mathcal{A} by its *induced action*

$$t \longrightarrow \alpha(\text{post}(\mathcal{A}, \gamma(t)))$$

- It is, more precisely, enough that we Approximate each action \mathcal{A} by an abstract action \mathcal{B} such that

$$\alpha(\text{post}(\mathcal{A}, \gamma(t))) = \text{post}(\mathcal{B}, t)$$

- **Example:** Let the set of concrete states be \mathcal{N} . Let the abstract domain be $\mathcal{P}(\{\text{even}, \text{odd}\})$. Define

$$\begin{aligned} \gamma(\text{even}) &= \{0, 2, 4, \dots\} \\ \gamma(\text{odd}) &= \{1, 3, 5, \dots\} \\ \gamma(\{\text{even}, \text{odd}\}) &= \mathcal{N} \\ \gamma(\emptyset) &= \emptyset \end{aligned}$$

- **Induced Operations:** can be tabled as follows:

Operator	Result on <i>even</i>	Result on <i>odd</i>
$\cdot + 1$	<i>odd</i>	<i>even</i>
$3 * \cdot$	<i>even</i>	<i>odd</i>
$\cdot / 2$	$\{\text{even}, \text{odd}\}$	\emptyset
<i>even</i> (\cdot)	<i>true</i>	<i>false</i>
<i>odd</i> (\cdot)	<i>false</i>	<i>true</i>

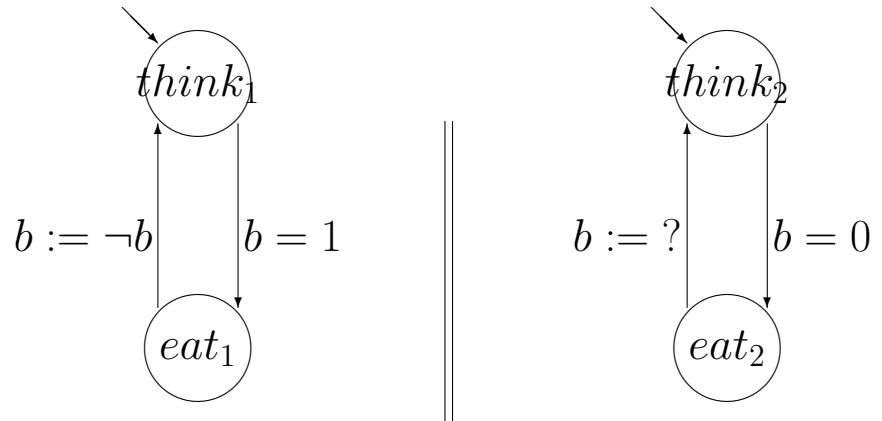
The table is extended to sets by

$$op(t_1 \sqcup t_2) = op(t_1) \sqcup op(t_2)$$

Abstract System

Action System *Dining Mathematicians*

declare b : bit
initially *true*



end

Problem: Check whether

$$\neg(at\ eat_1 \wedge at\ eat_2)$$

is invariant.

What about Liveness and Fairness?