

# Co-Algebraic HD-automata: Implementation of a Partitioning Algorithm

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joint work with

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# Plan of the talk

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- Principal data structures

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- The main cycle

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- Principal data structures
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- An example

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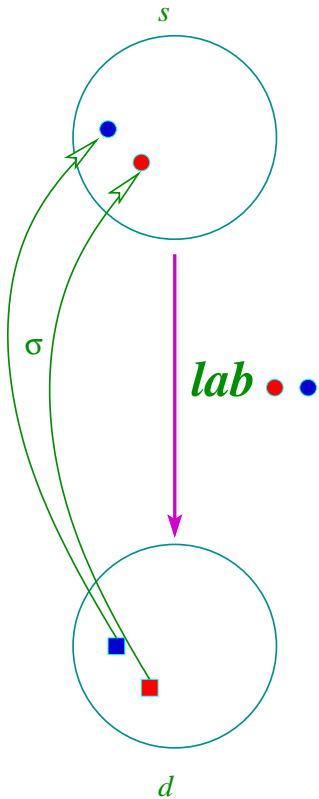
- Principal data structures
- The main cycle
- An example
- Final considerations

# States, labels & arrows

type  $\alpha$  state =

| Star

| State of  $\underbrace{\text{string}}_{\text{id}} * \underbrace{\alpha \text{ list}}_{\text{names}} * \underbrace{(\alpha \text{ list}) \text{ list}}_{\text{group}}$



type  $\alpha$  label =

| Tau of  $\alpha \text{ list}$

| BIn of  $\alpha \text{ list} * \alpha \text{ list}$

| BOut of  $\alpha \text{ list} * \alpha \text{ list}$

| In of  $\alpha \text{ list} * \alpha \text{ list}$

| Out of  $\alpha \text{ list} * \alpha \text{ list}$

$\pi$

$\sigma$

type  $\alpha$  arrow =

Arrow of  $\underbrace{\alpha \text{ state}}_{\text{source}} * \underbrace{\alpha \text{ state}}_{\text{dest}} * \underbrace{\alpha \text{ label}}_{\text{lab}}$

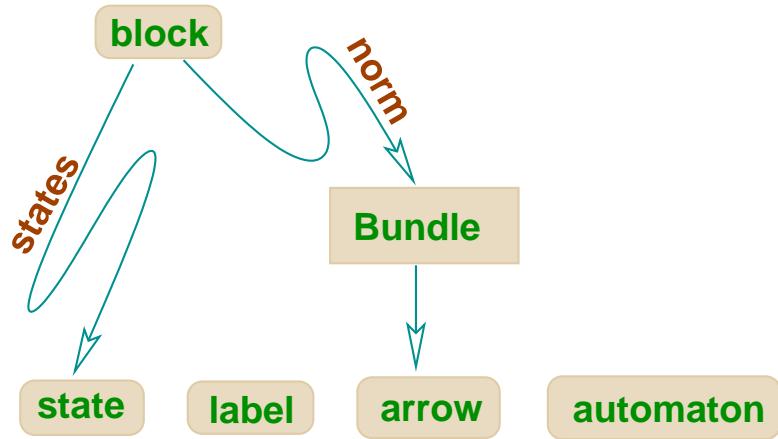
# Bundle & Automata

bundle :  $\underbrace{(\alpha \text{ arrow}) \text{ list}}_{\text{with the same source}}$

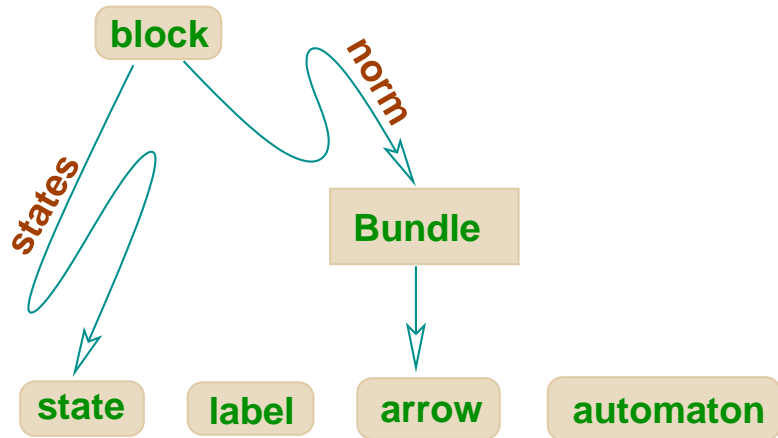
type  $\alpha$  automaton =  
HDAutoma of  $\underbrace{\alpha \text{ state}}_{\text{start}} * \underbrace{(\alpha \text{ state}) \text{ list}}_{\text{states}} * \underbrace{(\alpha \text{ arrow}) \text{ list}}_{\text{arrows}}$



# Blocks



# Blocks



At the end of each iteration,

- **blocks** represent the states of the  $n$ -th approximation of the minimal automaton while
- their **norm components** are the arrows of the approximation

# Blocks (2)

type  $\alpha$  blocks =

Block of

states :  $\alpha$  state list \*

norm :  $\alpha$  arrow list \*

active\_names :  $\alpha$  list \*

group :  $\alpha$  list list \*

$\Sigma$  :  $(\alpha$  state  $\rightarrow (\alpha * \alpha)$  list list) \*

$\Theta^{-1}$  :  $(\alpha$  state  $\rightarrow (\alpha * \alpha)$  list)

# Blocks (2)

type  $\alpha$  blocks =

Block of

states

:  $\alpha$  state list \*

norm

:  $\alpha$  arrow list \*

active\_names

:  $\alpha$  list \*

group

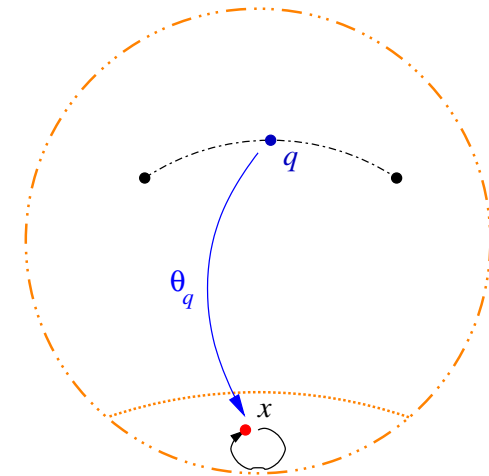
:  $\alpha$  list list \*

$\Sigma$

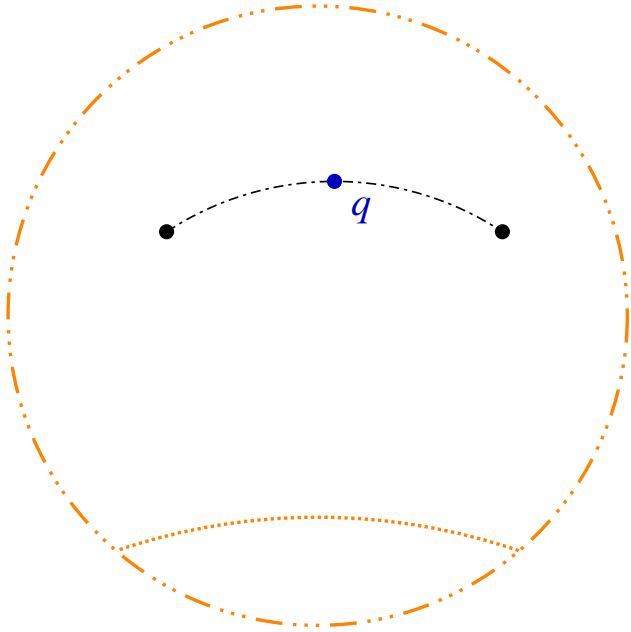
:  $(\alpha \text{ state} \rightarrow (\alpha * \alpha) \text{ list list}) *$

$\Theta^{-1}$

:  $(\alpha \text{ state} \rightarrow (\alpha * \alpha) \text{ list})$



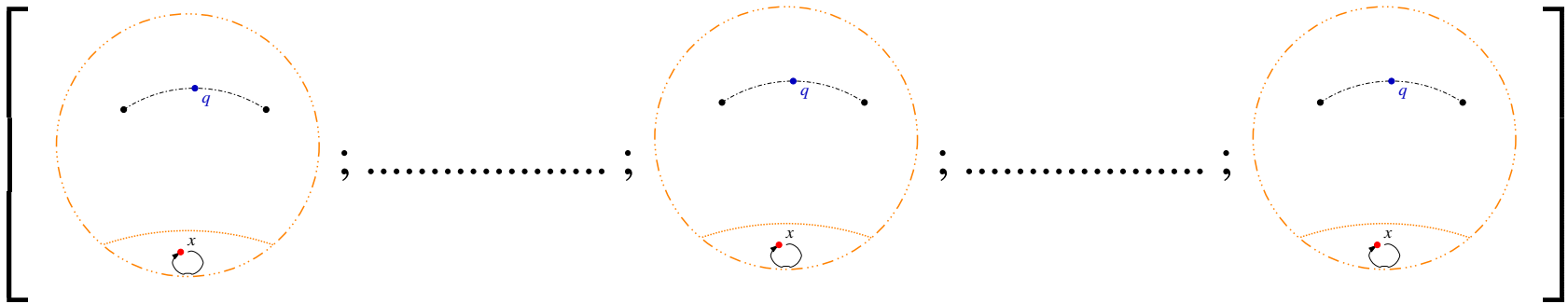
# Initially...



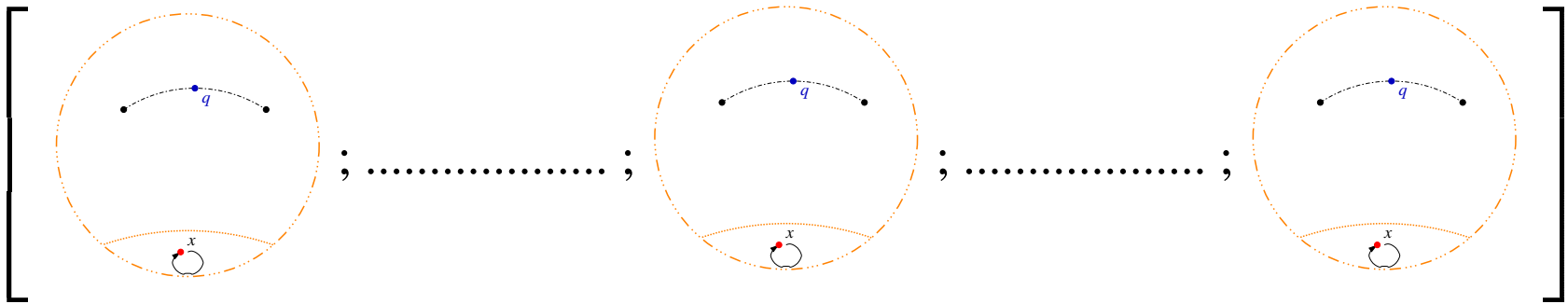
- All the states are (considered) bisimilar
- No norm, group or  $\theta$  is given

[ **Block**(states, [ ], [ ], [ ], (fun q → [ [ ] ]), (fun q → [ ])) ]

# Generic step

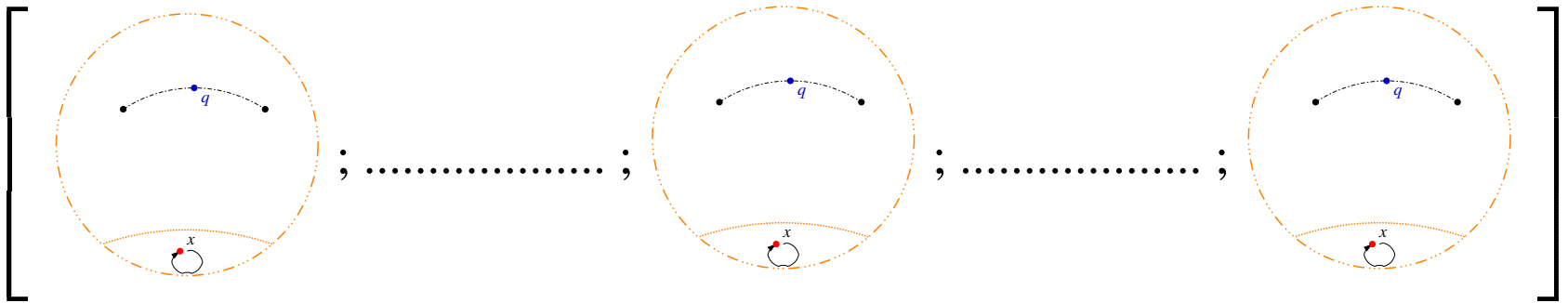


# Generic step

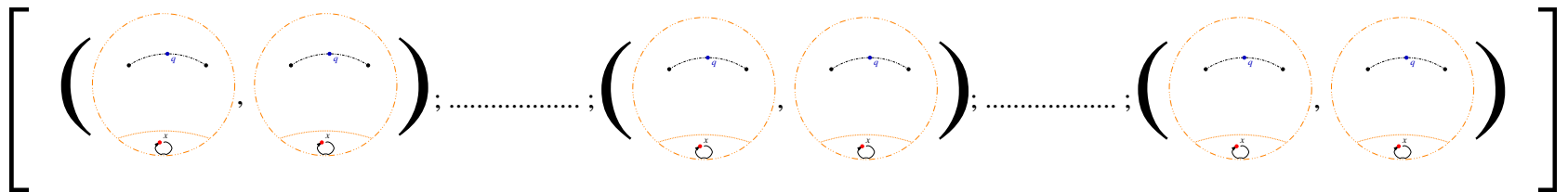


↓ split

# Generic step

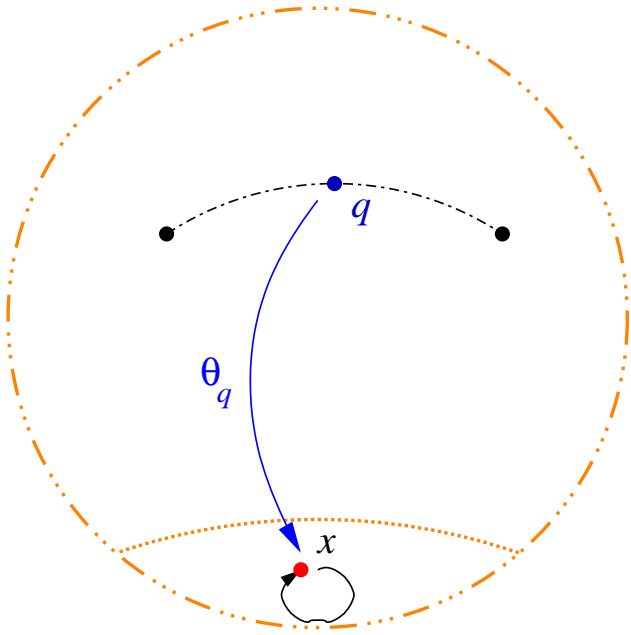


↓ split

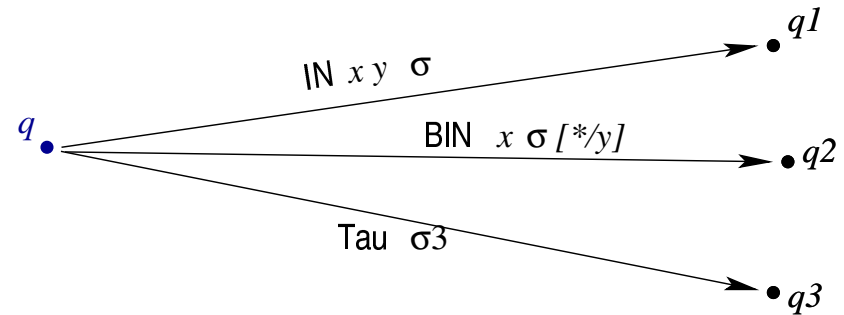
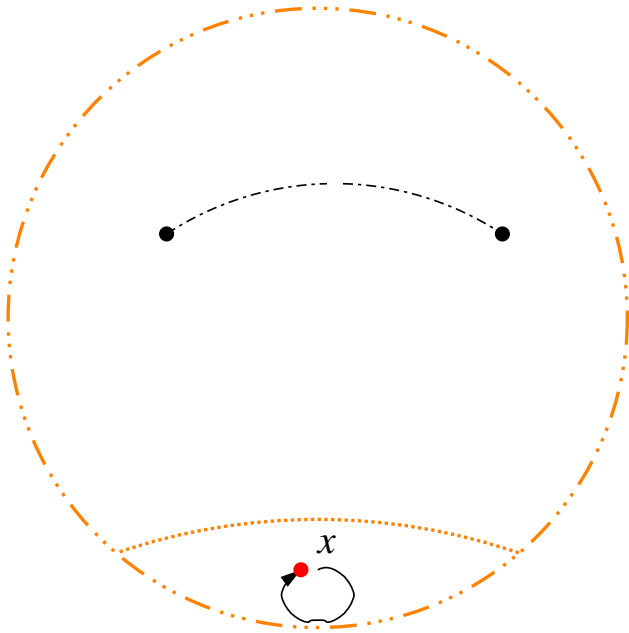




# Splitting: a closer look



# Splitting: a closer look

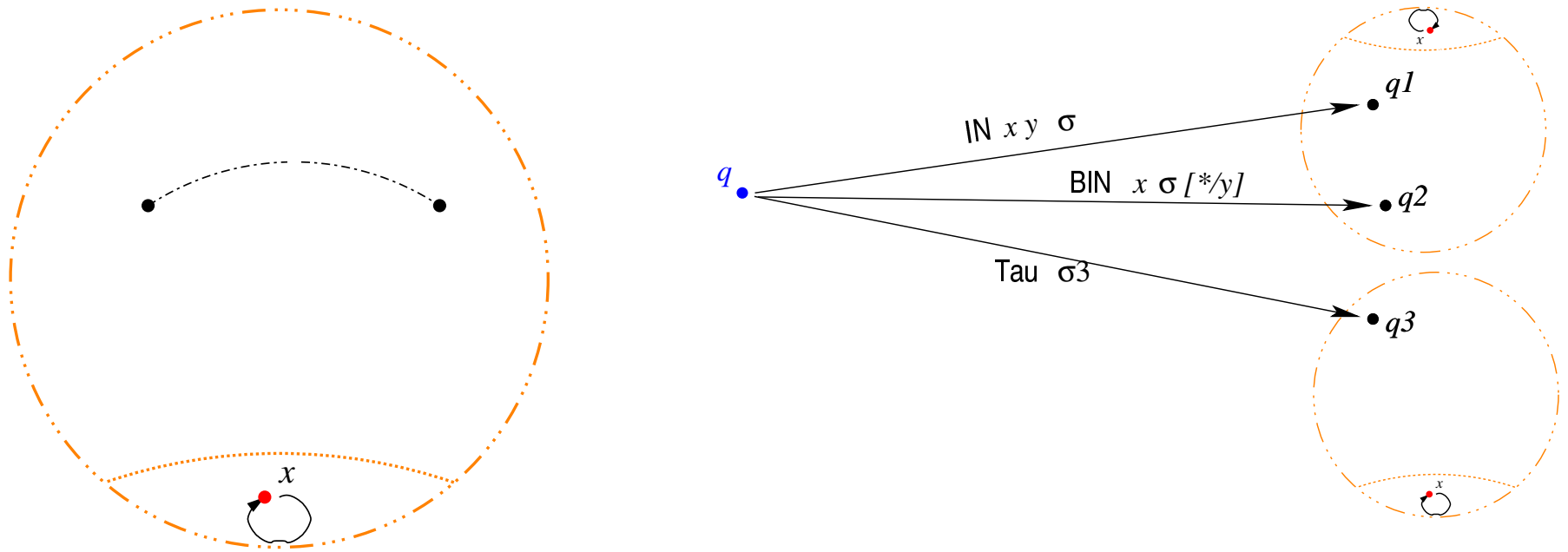


let bundle hd  $q$  =

List.sort compare

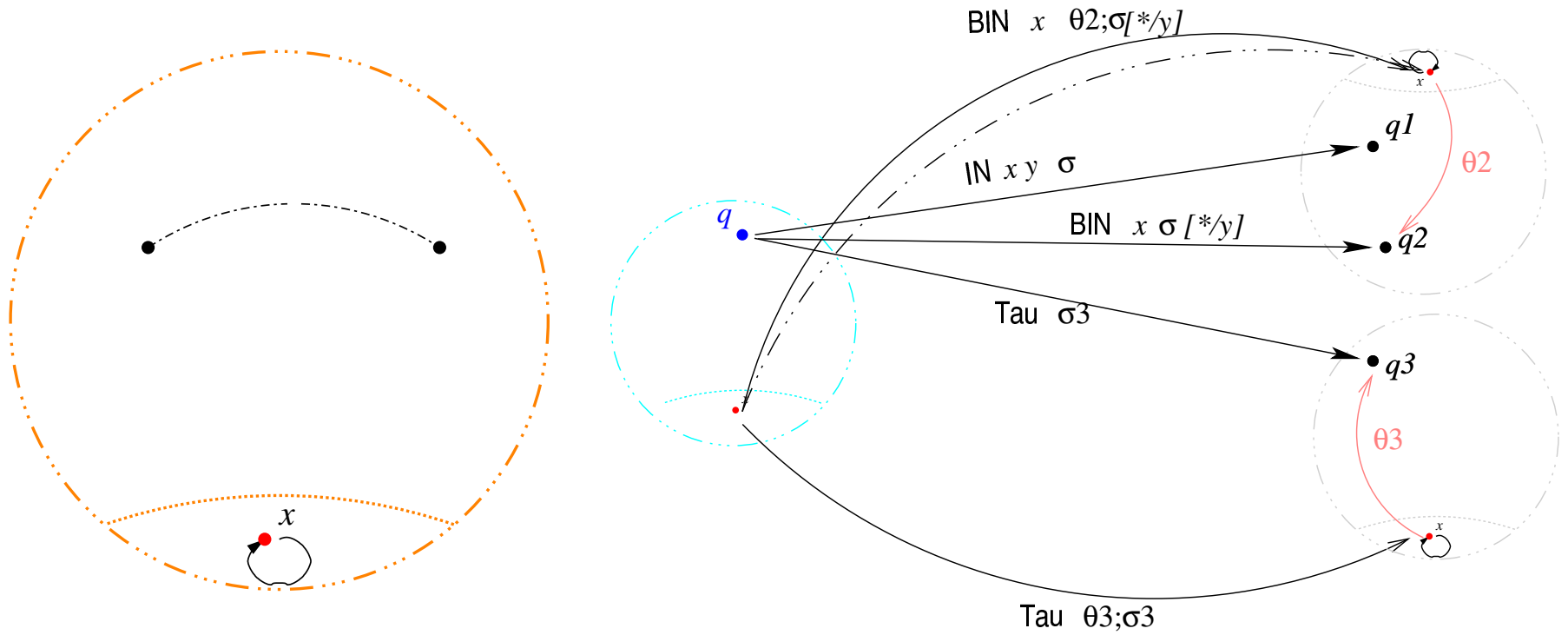
(List.filter (fun h  $\rightarrow$  (Arrow.source h) =  $q$ ) (arrows hd))

# Splitting: a closer look



List.map  $h_n$  bundle

# Splitting: a closer look



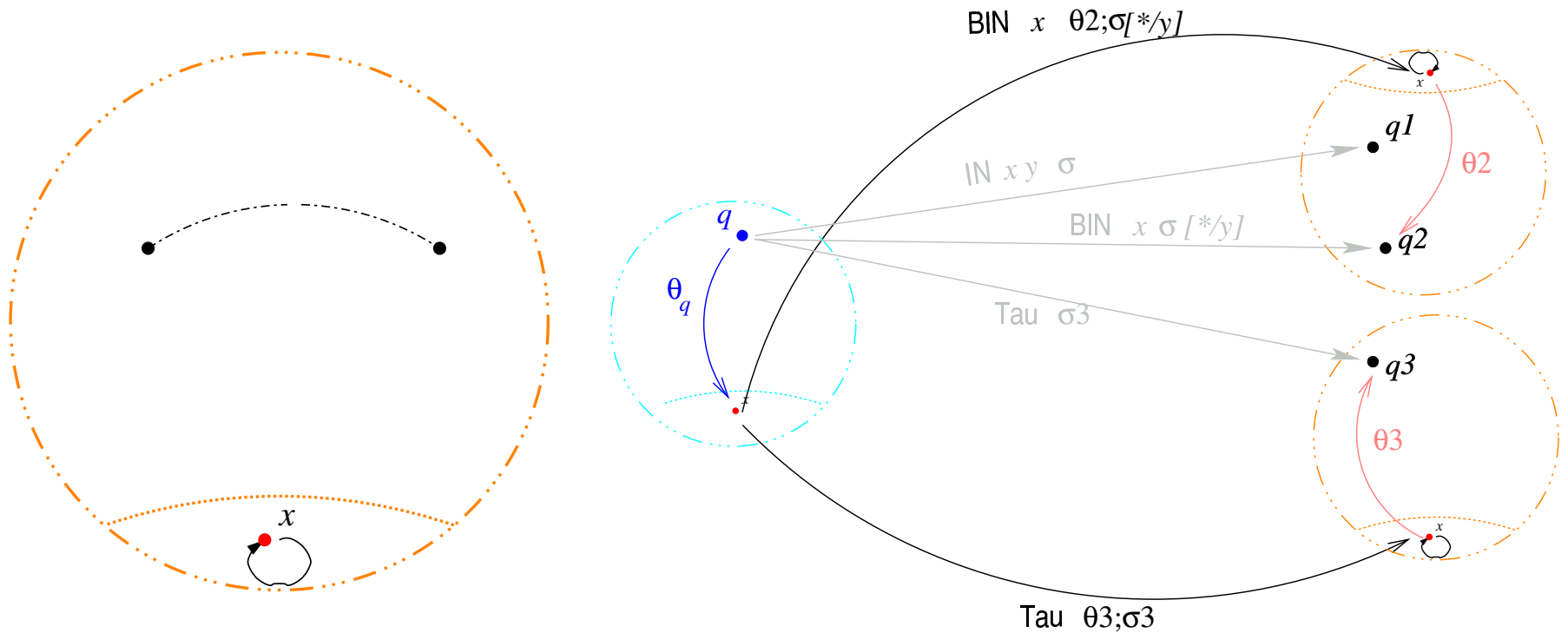
$$h_{n+1} = \mathit{norm} \langle \text{states}, \{ \langle \ell, \pi, h_n(q'), \sigma'; \sigma \rangle \mid q \xrightarrow{\ell \pi \sigma} q' \wedge \sigma' \in \Sigma_n(q') \} \rangle$$

let red bl = .....

let bl\_in = List.filter covered\_in bl

in list\_diff bl bl\_in

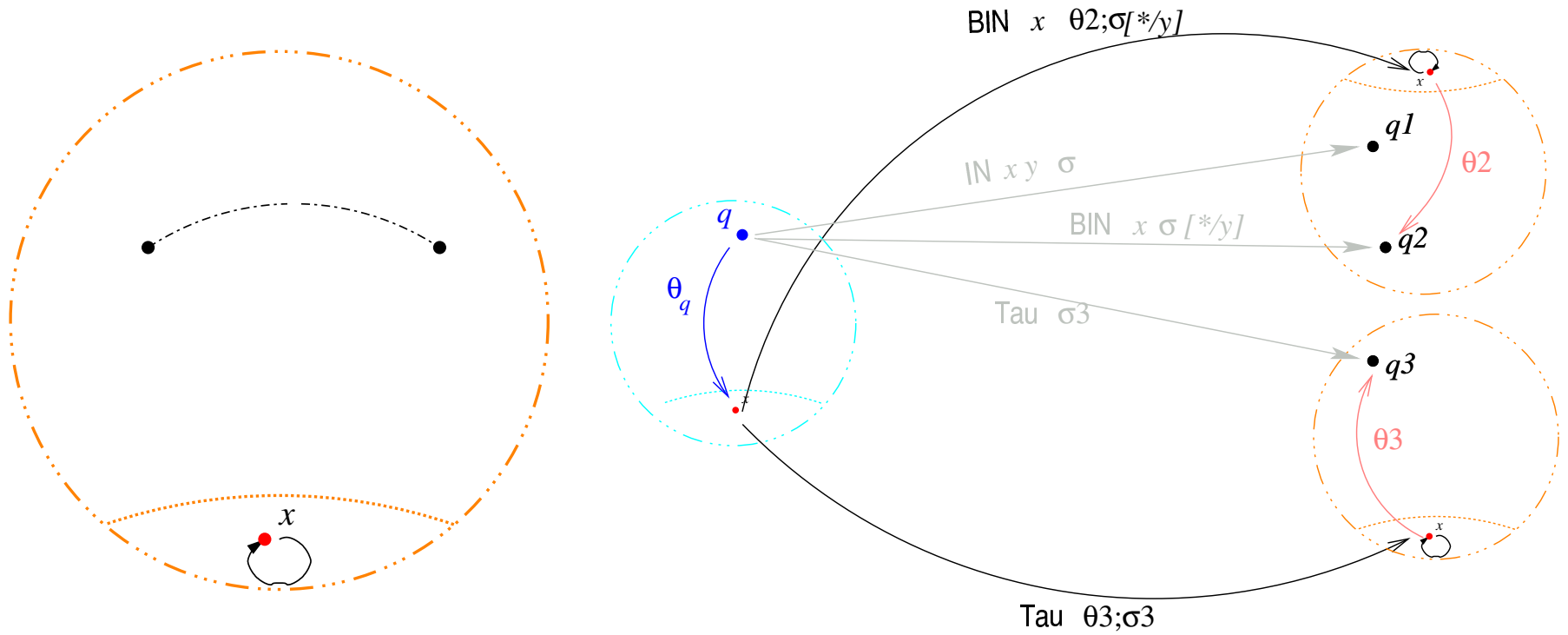
# Splitting: a closer look



```

let an = active_names_bundle (red bundle) in
let remove_in ar = match ar with
| Arrow(_,_,In(_,_)) → not (List.mem (obj ar) an)
| _ → false in
list_diff bundle (List.filter remove_in bundle)
  
```

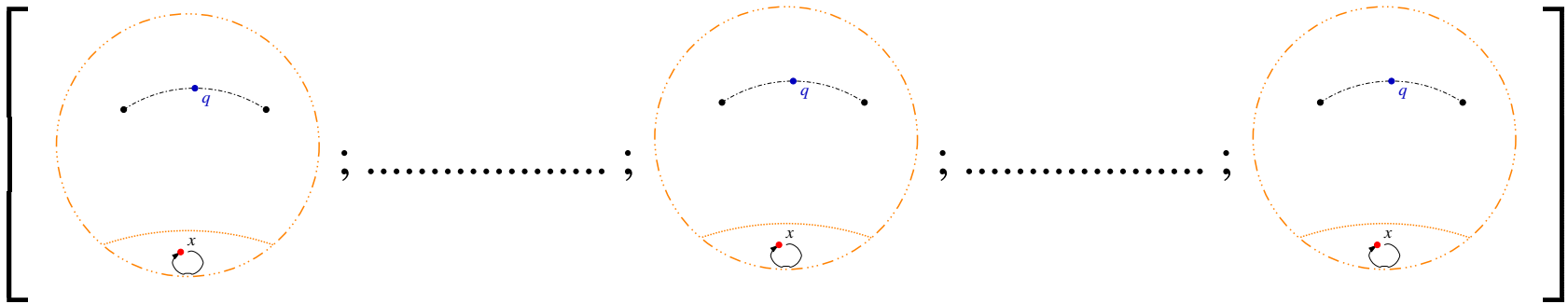
# Splitting: a closer look



$$\Sigma_{n+1}(q) = (\text{compute\_group}(\text{norm bundle})) ; \theta_q^{-1}$$

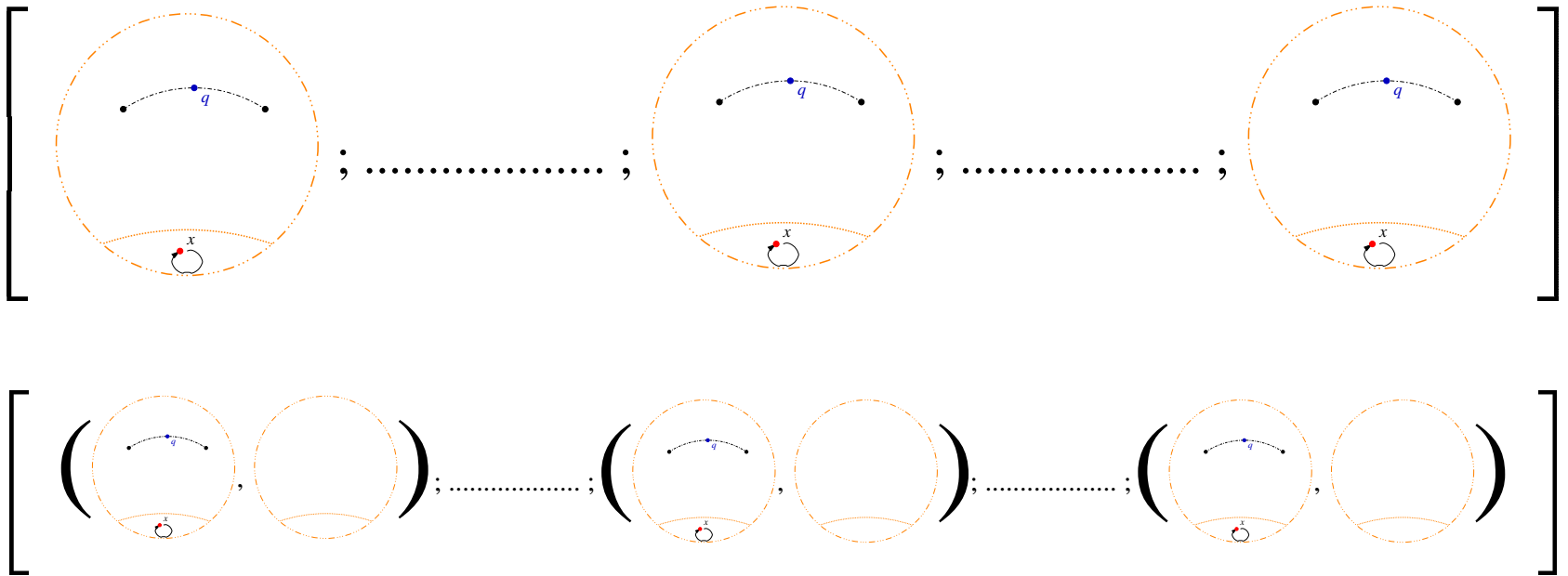
# Termination

...informally, when  $H_{n+1}$  is isomorph to  $H_n$



# Termination

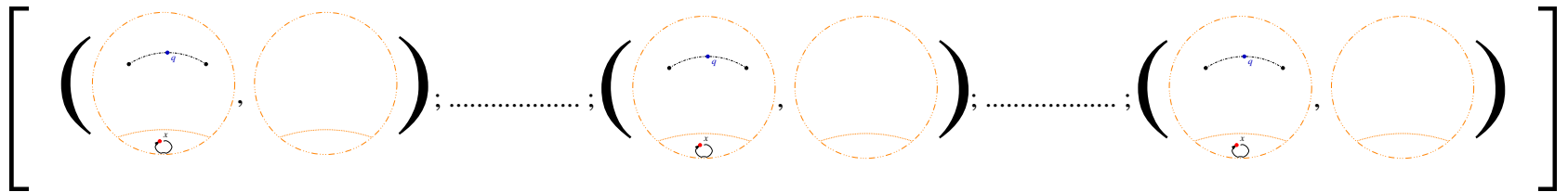
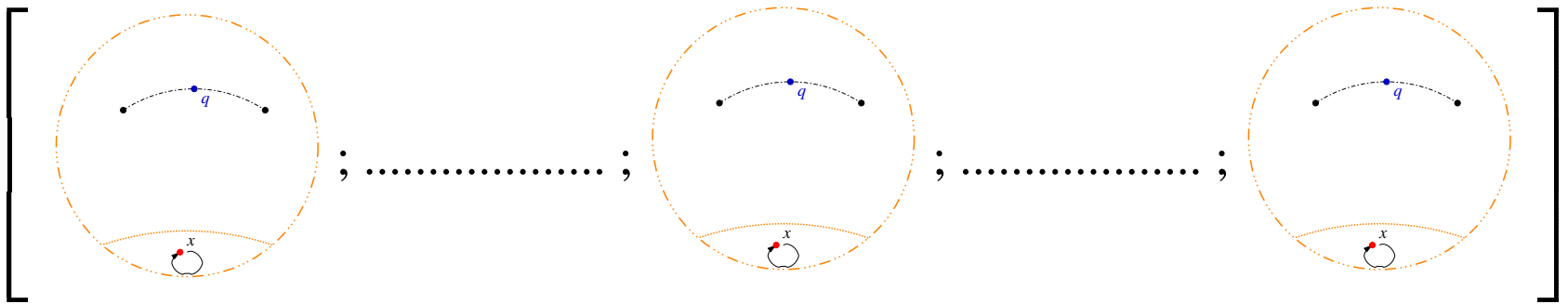
...informally, when  $H_{n+1}$  is isomorph to  $H_n$





# Termination

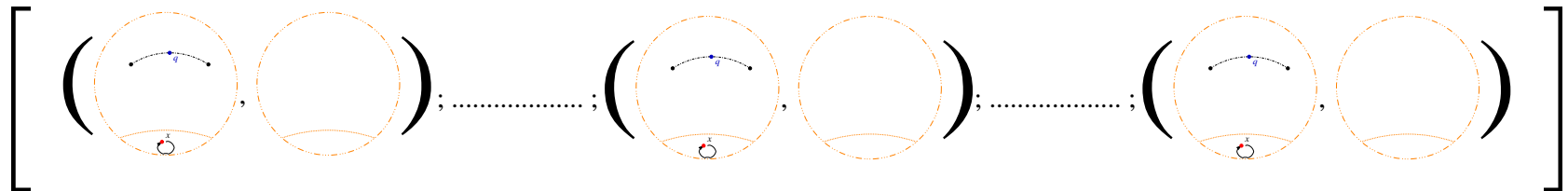
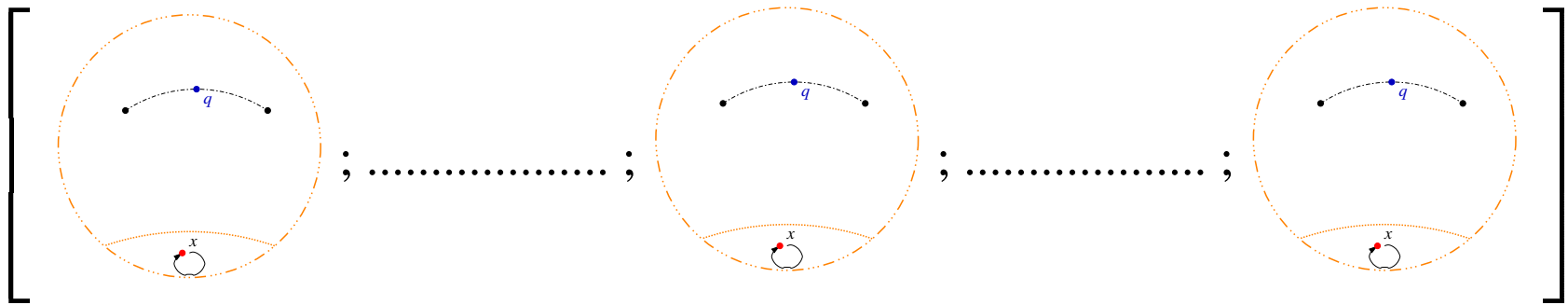
...informally, when  $H_{n+1}$  is isomorph to  $H_n$



$\wedge$

# Termination

...informally, when  $H_{n+1}$  is isomorph to  $H_n$



$\wedge$

no further names are added

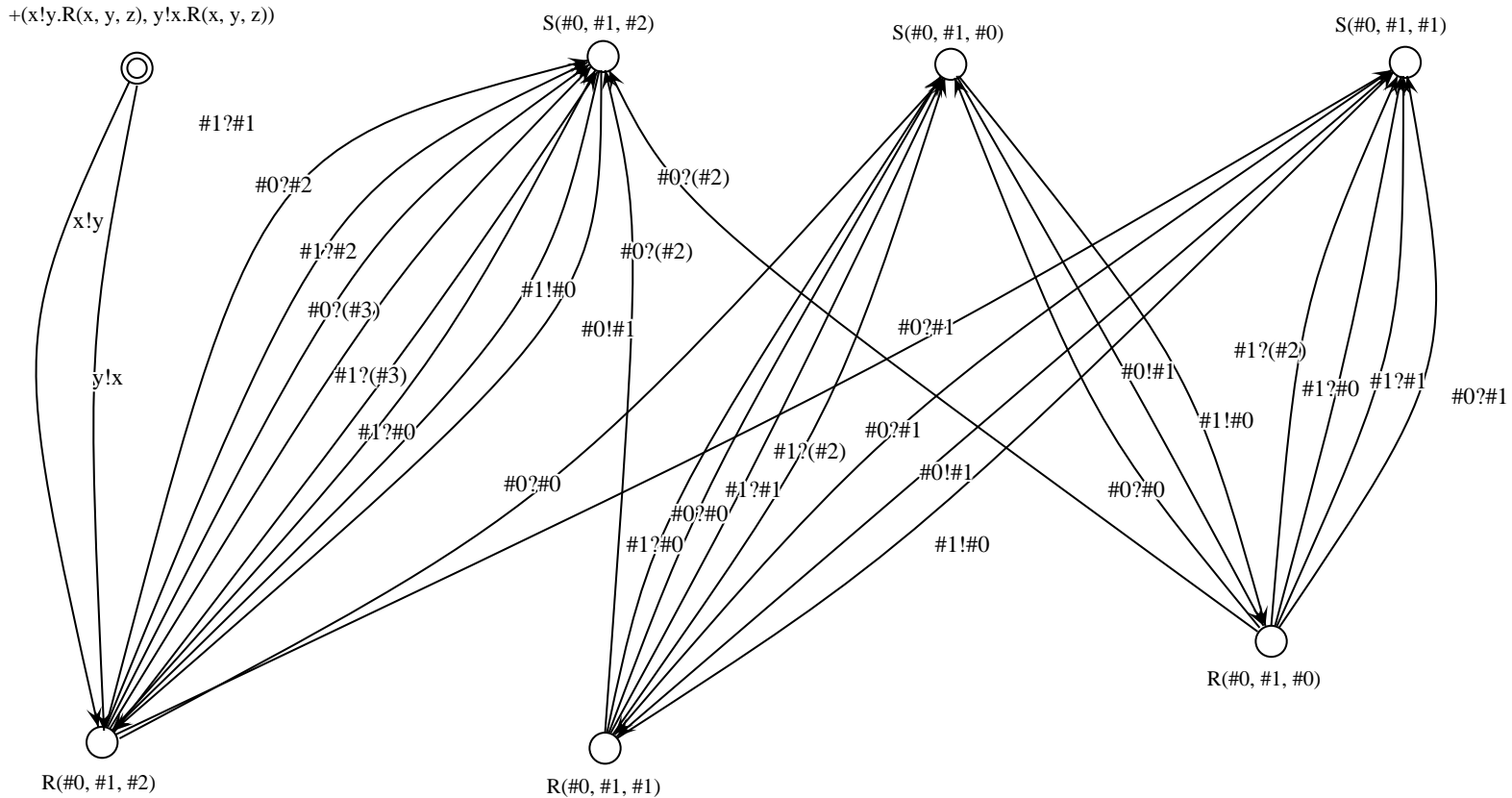
# An example

$$S(x, y, z) = x!y.R(x, y, z) + y!x.R(x, y, z)$$
$$R(x, y, z) = x?(w).S(x, y, w) + y?(w).S(y, x, z)$$

# An example

$$S(x, y, z) = x!y.R(x, y, z) + y!x.R(x, y, z)$$

$$R(x, y, z) = x?(w).S(x, y, w) + y?(w).S(y, x, z)$$



# Minimal representation

state	b0	2			
state	b1	2			
b0	→	b1	out	$\begin{bmatrix} 1 & : & 2 \\ & & \end{bmatrix}$	$\left[ \begin{array}{l} \begin{bmatrix} 1 & : & 2 \\ 1 & : & 2 \end{bmatrix} ; \begin{bmatrix} 2 & : & 1 \\ 2 & : & 1 \end{bmatrix} \\ \begin{bmatrix} 1 & : & 2 \\ 2 & : & 1 \\ 1 & : & 2 \\ 2 & : & 1 \\ 1 & : & 2 \\ 1 & : & 2 \\ 1 & : & 2 \\ 1 & : & 2 \\ 2 & : & 1 \\ 2 & : & 1 \\ 1 & : & 2 \\ 2 & : & 1 \\ 1 & : & 2 \\ 2 & : & 1 \\ 1 & : & 2 \\ 2 & : & 1 \end{array} \right]$
b0	→	b1	out	$\begin{bmatrix} 1 & : & 2 \\ & & \end{bmatrix}$	
b0	→	b1	out	$\begin{bmatrix} 2 & : & 1 \\ & & \end{bmatrix}$	
b0	→	b1	out	$\begin{bmatrix} 2 & : & 1 \\ & & \end{bmatrix}$	
b1	→	b0	bin	$\begin{bmatrix} 1 \\ & & \end{bmatrix}$	
b1	→	b0	bin	$\begin{bmatrix} 1 \\ & & \end{bmatrix}$	
b1	→	b0	bin	$\begin{bmatrix} 2 \\ & & \end{bmatrix}$	
b1	→	b0	bin	$\begin{bmatrix} 2 \\ & & \end{bmatrix}$	
b1	→	b0	in	$\begin{bmatrix} 1 & : & 1 \\ & & \end{bmatrix}$	
b1	→	b0	in	$\begin{bmatrix} 1 & : & 1 \\ & & \end{bmatrix}$	
b1	→	b0	in	$\begin{bmatrix} 1 & : & 2 \\ & & \end{bmatrix}$	
b1	→	b0	in	$\begin{bmatrix} 1 & : & 2 \\ & & \end{bmatrix}$	
b1	→	b0	in	$\begin{bmatrix} 2 & : & 1 \\ & & \end{bmatrix}$	
b1	→	b0	in	$\begin{bmatrix} 2 & : & 1 \\ & & \end{bmatrix}$	
b1	→	b0	in	$\begin{bmatrix} 2 & : & 2 \\ & & \end{bmatrix}$	

# Final remarks

- Extend to
  - open bisimilarity
  - asynchronous  $\pi$ -calculus
  - complex terms
- Try *big* automata
- Optimization: handling of permutations
- Integrations (HAL and Mobility workbench)
- Ocaml compiler