Refinement-based Exact Response-Time Analysis

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Joint work with Nan Guan and Wang Yi

Response-Time Analysis



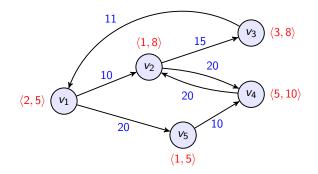
- Useful for
 - Schedulability analysis
 - Jitters in larger systems
 - . . .
- Standard RTA for static priorities + periodic/sporadic tasks

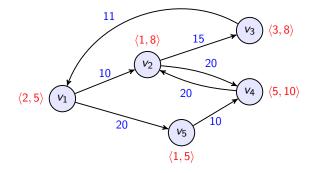
$$R_j = C_j + \sum_{i \in hp(j)} \left\lceil \frac{R_j}{T_i} \right\rceil C_i$$

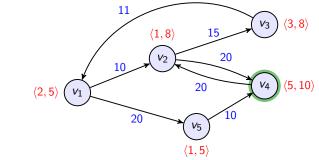
Not everything is periodic!

The Digraph Real-Time (DRT) Task Model (S. et al., RTAS 2011)

- Generalizes periodic, sporadic, GMF, RRT,
- Directed graph for each task
 - Vertices v: jobs to be released (with WCET and deadline)
 - Edges (u, v): minimum inter-release delays p(u, v)

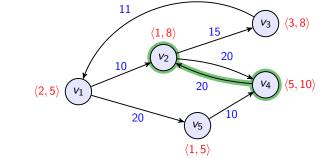




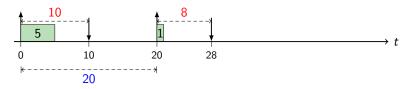


Path $\pi = (v_4)$

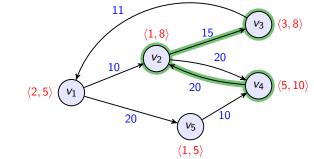




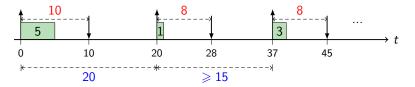
Path $\pi = (v_4, v_2)$



Martin Stigge

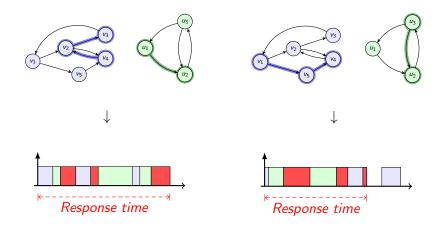


Path
$$\pi = (v_4, v_2, v_3)$$

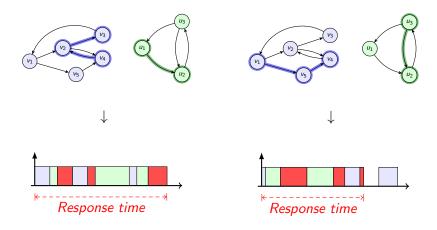


Response-Time Analysis for DRT

Problem: Path Combinations



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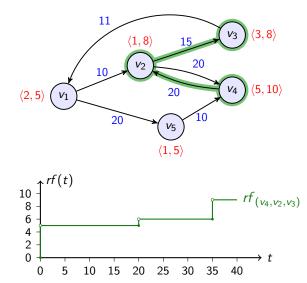
Combinatorial Explosion!

Fahrplan

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Step 1: From Paths to Functions

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Request Functions

Useful for deriving response time:

$$R_{SP}(v, \bar{rf}) = \min\left\{t \ge 0 \mid e(v) + \sum_{T' > T} rf^{(T')}(t) \le t\right\}$$
$$R_{SP}(v) = \max_{\bar{rf} \in RF(\tau)} R_{SP}(v, \bar{rf})$$

Request Functions

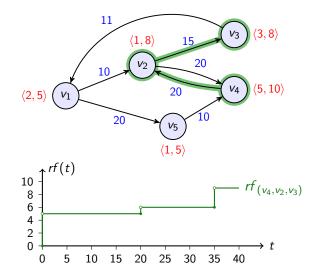
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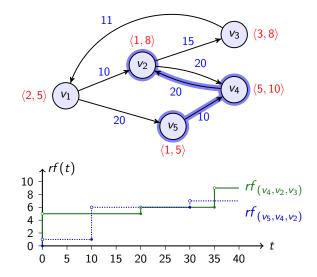
Combinatorial Explosion?!

Step 2: Abstraction Trees

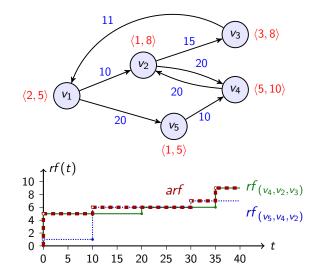
Abstract Request Functions

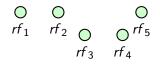


Abstract Request Functions

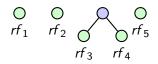


Abstract Request Functions

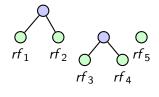




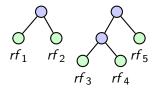
- Leaves are concrete *rf*
- Each node: maximum function of child nodes
- Root is maximum of all rf



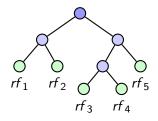
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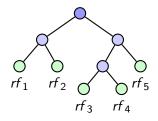
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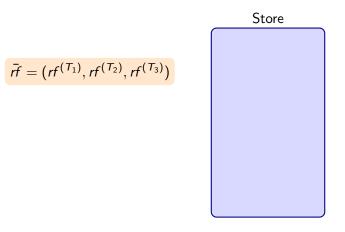


Define an abstraction tree per task:

- Leaves are concrete rf
- Each node: maximum function of child nodes
- Root is maximum of all rf

Allows stepwise refinement!

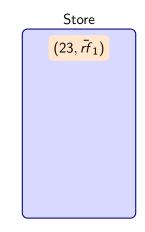
Tuple:

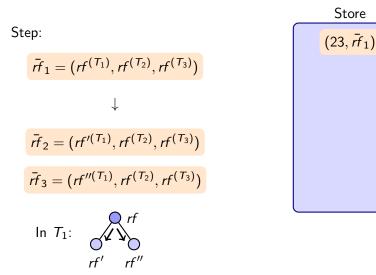


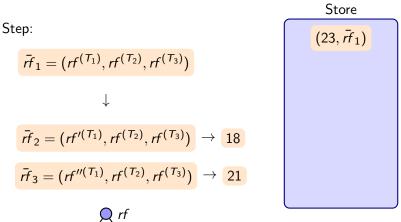
Tuple:
$$r\bar{f} = (rf^{(T_1)}, rf^{(T_2)}, rf^{(T_3)})$$

 \downarrow
Response time: $R_{SP}(v, r\bar{f}) = 23$

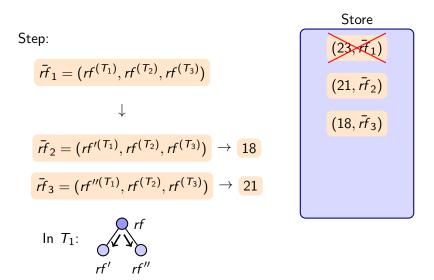
Using:
$$R_{SP}(v, \bar{r}f) = \min\left\{t \ge 0 \mid e(v) + \sum_{T' > T} rf^{(T')}(t) \le t\right\}$$

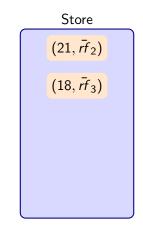




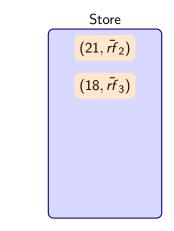


In
$$T_1$$
:

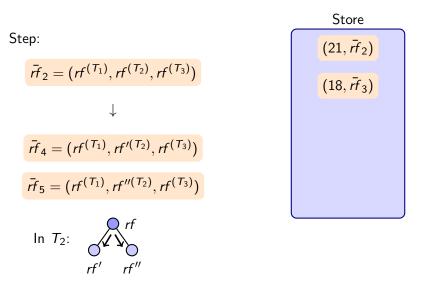




 $\bar{rf}_2 = (rf^{(T_1)}, rf^{(T_2)}, rf^{(T_3)})$



Step:



Step:

$$\bar{rf}_2 = (rf^{(T_1)}, rf^{(T_2)}, rf^{(T_3)})$$

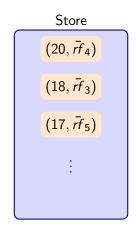
 \downarrow
 $\bar{rf}_4 = (rf^{(T_1)}, rf'^{(T_2)}, rf^{(T_3)}) \rightarrow 20$
 $\bar{rf}_5 = (rf^{(T_1)}, rf''^{(T_2)}, rf^{(T_3)}) \rightarrow 17$
 \bigcirc rf

In
$$T_2$$
:

Step:

$$\vec{rf}_2 = (rf^{(T_1)}, rf^{(T_2)}, rf^{(T_3)})$$

 \downarrow
 $\vec{rf}_4 = (rf^{(T_1)}, rf'^{(T_2)}, rf^{(T_3)}) \rightarrow 20$
 $\vec{rf}_5 = (rf^{(T_1)}, rf''^{(T_2)}, rf^{(T_3)}) \rightarrow 17$
 $\ln T_2:$
 $rf' rf''$



Initialization:

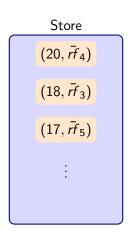
Most abstract functions

Each iteration:

• Replace functions along *abstraction trees*

Termination:

• All functions are concrete



Initialization:

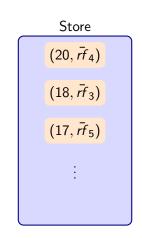
Most abstract functions

Each iteration:

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Initialization:

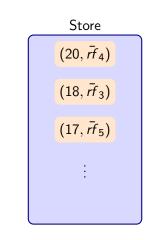
Most abstract functions

Each iteration:

• Replace functions along *abstraction trees*

Termination:

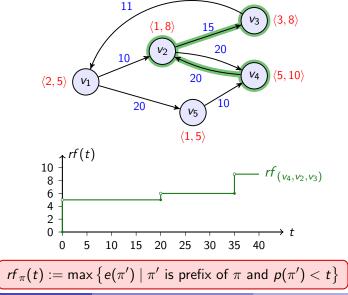
• All functions are concrete



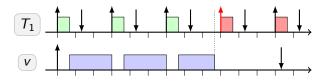
Pluggable Path Abstractions!

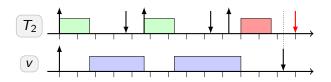
Path Abstractions: SP + EDF

Path Abstractions: Static Priorities

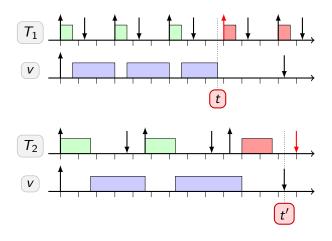


Path Abstractions: EDF





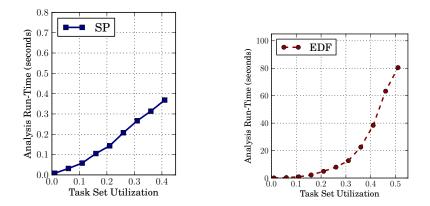
Path Abstractions: EDF



 $wf_{\pi}(t,t') := \max\{e(\pi') \mid \pi' ext{ is prefix of } \pi, \ p(\pi') < t ext{ and } d(\pi') \leqslant t'\}.$

Evaluation

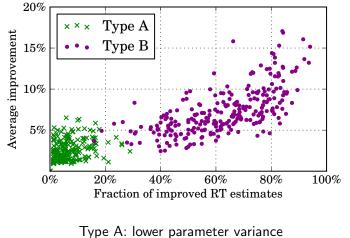
Evaluation: Run-time Scaling



10-20 tasks with 5-10 vertices each, branching degree 1-3

(Busy window extension for EDF.)

Evaluation: Precision Improvement

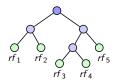


Type B: higher parameter variance

Summary

• Exact solution for NP-hard problem

- Efficient method
- Iterative refinement
- Pluggable path abstractions
 - Static Priorities
 - EDF
 - Flexible
- Ongoing work:
 - Apply to other problems



Q & A

Thanks!