Parallel & Concurrent Haskell 1:
Basic Pure Parallelism

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The parallelism landscape is getting crowded
- Every language has their own solution(s)
  - Erlang: asynchronous message-passing
  - Go: CSP
  - C: pthreads, OpenMP, TBB, ...
  - F#, C#: threads, async, ...

Some programming models are more suited to particular kinds of applications
- e.g. threads are good for interactive applications, less good for parallel algorithms
- Message-passing is good for distribution, less good for local consistency
Haskell’s approach

• We want to give you the right tool for the job
  – Even if that means having many tools
• But the overall philosophy is
  – provide *minimal* built-in functionality
  – implement nice abstraction layers on top

• How do you, the programmer, decide which tool (API) you need?
First, we divide the landscape in two: *Parallel* and *Concurrent* applications/programming models.

What’s the difference?
Parallelism vs. Concurrency

- Multiple cores for *performance*
- Multiple threads for *modularity of interaction*

Parallel Haskell

Concurrent Haskell
Parallelism vs. Concurrency

- Primary distinguishing feature of Parallel Haskell: **determinism**
  - The program always does the same thing, but may run faster when given multiple cores to run on.
  - No race conditions or deadlocks
  - Add parallelism without sacrificing correctness
  - Parallelism is used to speed up pure (non-IO monad) Haskell code
Parallelism vs. Concurrency

- Primary distinguishing feature of Concurrent Haskell: threads of control
  - Concurrent programming is done in the IO monad
    - because threads have effects
    - effects from multiple threads are interleaved nondeterministically at runtime.
  - Concurrent programming allows programs that interact with multiple external agents to be modular
    - the interaction with each agent is programmed separately
    - Allows programs to be structured as a collection of interacting agents (actors)
We have a lot of ground to cover...

1. Basic pure parallelism
2. The Par Monad
3. Concurrent Haskell
4. Software Transactional Memory
5. Server applications
6. Distributed programming
7. GPU programming
I. Parallel Haskell

- In this part of the course, you will learn how to:
  - Do basic parallelism:
    - compile and run a Haskell program, and measure its performance
    - parallelise a simple Haskell program (a Sudoku solver)
    - use ThreadScope to profile parallel execution
    - do dynamic partitioning
    - measure parallel speedup
      - use Amdahl’s law to calculate possible speedup
  - Work with Evaluation Strategies
    - build simple Strategies
Running example: solving Sudoku

- code from the Haskell wiki (brute force search with some intelligent pruning)
- can solve all 49,000 problems in 2 mins
- input: a line of text representing a problem

```haskell
import Sudoku

solve :: String -> Maybe Grid
```
Solving Sudoku problems

• Sequentially:
  – divide the file into lines
  – call the solver for each line

```haskell
main :: IO ()
main = do
  [f] <- getArgs
  grids <- fmap lines $ readFile f
  print $ length $ filter isJust $ map solve grids

solve :: String -> Maybe Grid
```
Compile the program...

```
$ ghc -O2 sudoku1.hs -rtsopts
[1 of 2] Compiling Sudoku           ( Sudoku.hs, Sudoku.o )
[2 of 2] Compiling Main             ( sudoku1.hs, sudoku1.o )
Linking sudoku1 ... 
$
```
Run the program...

```
$ ./sudoku1 sudoku17.1000.txt +RTS -s
  2,392,127,440 bytes allocated in the heap
  36,829,592 bytes copied during GC
   191,168 bytes maximum residency (11 sample(s))
   82,256 bytes maximum slop
  2 MB total memory in use (0 MB lost due to fragmentation)

Generation 0:  4570 collections,    0 parallel,   0.14s,   0.13s elapsed
Generation 1:    11 collections,    0 parallel,   0.00s,   0.00s elapsed

...```

```
INIT time    0.00s  (  0.00s elapsed)
MUT time    2.92s  (  2.92s elapsed)
GC time    0.14s  (  0.14s elapsed)
EXIT time    0.00s  (  0.00s elapsed)
Total time    3.06s  (  3.06s elapsed)
```

...
Now to parallelise it...

- Doing parallel computation entails specifying coordination in some way – compute $A$ in parallel with $B$
- This is a constraint on evaluation order
- But by design, Haskell does not have a specified evaluation order
- So we need to add something to the language to express constraints on evaluation order
The Eval monad

- **Eval** is pure
- Just for expressing sequencing between `rpar/rseq` – nothing more
- Compositional – larger **Eval** sequences can be built by composing smaller ones using monad combinators
- Internal workings of **Eval** are very simple (see Haskell Symposium 2010 paper)

```haskell
module Control.Parallel.Strategies (..) where

data Eval a
instance Monad Eval

runEval :: Eval a -> a
rpar :: a -> Eval a
rseq :: a -> Eval a
```

Start evaluating `a` (to WHNF) in the background
Evaluate `b` (to WHNF) and wait for the result
• We want to do a in parallel with b.
• Which of the following is the best?

```
  do
  a' <- rpar a
  b' <- rpar b
  return (a', b')

  do
  a' <- rpar a
  b' <- rseq b
  return (a', b')

  do
  a' <- rpar a
  b' <- rseq b
  rseq a'
  return (a', b')

  do
  a' <- rpar a
  b' <- rpar b
  rseq a'
  rseq b'
  return (a', b')
```
What does rpar actually do?

- rpar creates a spark by writing an entry in the spark pool
  - rpar is very cheap! (not a thread)
- the spark pool is a circular buffer
- when a processor has nothing to do, it tries to remove an entry from its own spark pool, or steal an entry from another spark pool (work stealing)
- when a spark is found, it is evaluated
- The spark pool can be full – new sparks are discarded when the pool is full. Watch out!
Parallelising Sudoku

• Let’s divide the work in two, so we can solve each half in parallel:

```haskell
let (as, bs) = splitAt (length grids `div` 2) grids
```

• Now we need something like

```haskell
runEval $ do
  as’ <- rpar (map solve as)
  bs’ <- rpar (map solve bs)
  rseq as’
  rseq bs’
  return (as’ ++ bs’)
```
But this won’t work...

- \texttt{rpar} evaluates its argument to Weak Head Normal Form (WHNF)
- what is WHNF?
  - evaluates as far as the \textit{first constructor}
  - e.g. for a list, we get either \([\ ]\) or \((x:xs)\)
  - e.g. WHNF of “\texttt{map solve (a:as)}” would be “\texttt{solve a : map solve as}”
- But we want to evaluate the whole list, and the elements

```haskell
runEval $ do
  as' <- rpar (map solve as)
  bs' <- rpar (map solve bs)
  rseq as'
  rseq bs'
  return (as' ++ bs')
```
We need to go deeper

```haskell
module Control.DeepSeq (..) where

class NFData a where
  rnf :: a -> ()
  deepseq :: NFData a => a -> b -> b
  deepseq a b = rnf a `seq` b

force :: NFData a => a -> a
force a = deepseq a a
```

- provided by the ‘deepseq’ package
- **force** fully evaluates a nested data structure and returns it
  - e.g. a list: the list is fully evaluated, including the elements
- uses overloading: the argument must be an instance of **NFData**
  - instances for most common types are provided by the library
Ok, adding force

Now we just need to evaluate this at the top level in ‘main’:

```haskell
runEval $ do
  as' <- rpar (force (map solve as))
  bs' <- rpar (force (map solve bs))
  rseq as'
  rseq bs'
  return (as' ++ bs')
```

```haskell
print $ length $ filter isJust $ runEval $ do
  as' <- rpar (force (map solve as))
  ...
```
Let’s try it...

$ ghc --make -O2 sudoku2.hs -rtsopts -threaded
[1 of 2] Compiling Sudoku           ( Sudoku.hs, Sudoku.o )
[2 of 2] Compiling Main             ( sudoku2.hs, sudoku2.o )
Linking sudoku2 ...
$
Run it on one processor first

```
$ ./sudoku2 sudoku17.1000.txt +RTS -s
./sudoku2 sudoku17.1000.txt +RTS -s
1000
    2,400,398,952 bytes allocated in the heap
    48,900,472 bytes copied during GC
    3,280,616 bytes maximum residency (7 sample(s))
    379,624 bytes maximum slop
    11 MB total memory in use (0 MB lost due to fragmentation)
```

...  

```
INIT time 0.00s  ( 0.00s elapsed)
MUT time  2.91s  ( 2.91s elapsed)
GC time   0.19s  ( 0.19s elapsed)
EXIT time 0.00s  ( 0.00s elapsed)
Total time 3.09s  ( 3.09s elapsed)
```

...  

A tiny bit slower (was 3.06 before). Splitting and reconstructing the list has some overhead.
$ ./sudoku2 sudoku17.1000.txt +RTS -N2 -s

2,400,125,664 bytes allocated in the heap
48,845,008 bytes copied during GC
2,617,120 bytes maximum residency (7 sample(s))
313,496 bytes maximum slop
9 MB total memory in use (0 MB lost due to fragmentation)

Generation 0: 2975 collections, 2974 parallel, 1.04s, 0.15s elapsed
Generation 1: 7 collections, 7 parallel, 0.05s, 0.02s elapsed

Parallel GC work balance: 1.52 (6087267 / 3999565, ideal 2)

SPARKS: 2 (1 converted, 0 pruned)

INIT time   0.00s  (  0.00s elapsed)
MUT time    2.21s  (  1.80s elapsed)
GC time     1.08s  (  0.17s elapsed)
EXIT time   0.00s  (  0.00s elapsed)
Total time  3.29s  (  1.97s elapsed)
Calculating Speedup

- Calculating speedup with 2 processors:
  - Elapsed time (1 proc) / Elapsed Time (2 procs)
  - NB. not CPU time (2 procs) / Elapsed (2 procs)!
  - NB. compare against sequential program, not parallel program running on 1 proc
    - why? introducing parallelism may add some overhead compared to the sequential version

- Speedup for sudoku2: 3.06/1.97 = 1.55
  - not great...
Why not 2?

• there are two reasons for lack of parallel speedup:
  – less than 100% utilisation (some processors idle for part of the time)
  – extra overhead in the parallel version
• Each of these has many possible causes...
A menu of ways to go wrong

• less than 100% utilisation
  – parallelism was not created, or was discarded
  – algorithm not fully parallelised – residual sequential computation
  – uneven work loads

• extra overhead in the parallel version
  – overheads from rpar, work-stealing, force, ...
  – larger memory requirements leads to GC overhead

• low-level issues that are Simon’s problem:
  – poor scheduling
  – communication latency
  – GC synchronisation
  – duplicating work
  – poor locality, cache effects
So we need *tools*

- to tell us why the program isn’t performing as well as it could be
- For Parallel Haskell we have ThreadScope

```bash
$ rm sudoku2; ghc -O2 sudoku2.hs -threaded -rtsopts -eventlog
$ ./sudoku2 sudoku17.1000.txt +RTS -N2 -l s
$ threadscope sudoku2.eventlog
```

- `-eventlog` has very little effect on runtime
  – important for profiling parallelism
Uneven workloads...

- So one of the tasks took longer than the other, leading to less than 100% utilisation

```haskell
let (as, bs) = splitAt (length grids `div` 2) grids
```

- One of these lists contains more work than the other, even though they have the same length
  - sudoku solving is not a constant-time task: it is a searching problem, so it depends on how quickly the search finds the solution
Partitioning

• Dividing up the work along fixed pre-defined boundaries, as we did here, is called static partitioning
  – static partitioning is simple, but can lead to under-utilisation if the tasks can vary in size
  – static partitioning does not adapt to varying availability of processors – our solution here can use only 2 processors

\[
\text{let } (\text{as}, \text{bs}) = \text{splitAt (length grids `div` 2) grids}
\]
Dynamic Partitioning

• Dynamic partitioning involves
  – dividing the work into smaller units
  – assigning work units to processors dynamically at runtime using a *scheduler*
  – good for irregular problems and varying number of processors

• GHC’s runtime system provides spark pools to track the work units, and a work-stealing scheduler to assign them to processors

• So all we need to do is use smaller tasks and more sparks, and we get dynamic partitioning
Revisiting Sudoku...

• So previously we had this:

  ```haskell
  runEval $ do
      a <- rpar (force (map solve as))
      b <- rpar (force (map solve bs))
      ...
  ```

• We want to push `rpar` down into the `map`
  – so each call to solve will be a separate spark
A parallel map

\[
\text{parMap} :: (a \rightarrow b) \rightarrow [a] \rightarrow \text{Eval} [b]
\]
\[
\text{parMap } f \; [] = \text{return} \; []
\]
\[
\text{parMap } f \; (a : as) = \begin{aligned}
    & b \leftarrow \text{rpar} \; (f \; a) \\
    & bs \leftarrow \text{parMap} \; f \; as \\
    & \text{return} \; (b : bs)
\end{aligned}
\]

- Provided by Control.Parallel.Strategies
- Also:

\[
\text{parMap } f \; xs = \text{mapM} \; (\text{rpar} \; . \; f) \; xs
\]
Putting it together...

- Code is simpler than the static partitioning version!
Results

./sudoku3 sudoku17.1000.txt +RTS -s -N2 -ls
  2,401,880,544 bytes allocated in the heap
  49,256,128 bytes copied during GC
  2,144,728 bytes maximum residency (13 sample(s))
  198,944 bytes maximum slop
  7 MB total memory in use (0 MB lost due to fragmentation)

Generation 0: 2495 collections, 2494 parallel, 1.21s, 0.17s elapsed
Generation 1: 13 collections, 13 parallel, 0.06s, 0.02s elapsed

Parallel GC work balance: 1.64 (6139564 / 3750823, ideal 2)

SPARKS: 1000 (1000 converted, 0 pruned)

INIT time  0.00s  (  0.00s elapsed)
MUT time   2.19s  (  1.55s elapsed)
GC time   1.27s  (  0.19s elapsed)
EXIT time  0.00s  (  0.00s elapsed)
Total time  3.46s  (  1.74s elapsed)

Now 1.7 speedup
5.2 speedup
• Lots of GC
• One core doing all the GC work
  – indicates one core generating lots of data
• Are there any sequential parts of this program?
• `readFile` and `lines` are not parallelised
• Suppose we force the sequential parts to happen first...

```haskell
main :: IO ()
main = do
  [f] <- getArgs
  grids <- fmap lines $ readFile f
  evaluate (length grids)
  print $ length $ filter isJust $ runEval $ parMap solve grids
```
Calculating possible speedup

- When part of the program is sequential, Amdahl’s law tells us what the maximum speedup is.

\[
\frac{1}{(1 - P) + \frac{P}{N}}
\]

- $P =$ parallel portion of runtime
- $N =$ number of processors
Applying Amdahl’s law

• In our case:
  – runtime = 3.06s (NB. sequential runtime!)
  – non-parallel portion = 0.038s (P = 0.9876)
  – N = 2, max speedup = 1 / ((1 − 0.9876) + 0.9876/2)
    • =~ 1.98
    • on 2 processors, maximum speedup is not affected much by this sequential portion
  – N = 64, max speedup = 35.93
    • on 64 processors, 38ms of sequential execution has a dramatic effect on speedup
• diminishing returns...
• See “Amdahl's Law in the Multicore Era”, Mark Hill & Michael R. Marty
• Amdahl’s law paints a bleak picture
  – speedup gets increasingly hard to achieve as we add more cores
  – returns diminish quickly when more cores are added
  – small amounts of sequential execution have a dramatic effect
  – proposed solutions include heterogeneity in the cores
    – likely to create bigger problems for programmers
• See also Gustafson’s law – the situation might not be as bleak as Amdahl’s law suggests:
  – with more processors, you can solve a bigger problem
  – the sequential portion is often fixed or grows slowly with problem size
• Note: in Haskell it is hard to identify the sequential parts anyway, due to lazy evaluation
Evaluation Strategies

• So far we have used Eval/rpar/rseq
  – these are quite low-level tools
  – but it’s important to understand how the underlying mechanisms work
• Now, we will raise the level of abstraction
• Goal: encapsulate parallel idioms as re-usable components that can be composed together.
The Strategy type

\[
\text{type } \text{Strategy } a = a \rightarrow \text{Eval } a
\]

• **Strategy** \( a \) is a function that:
  – when applied to a value \( a \),
  – evaluates \( a \) to some degree
  – (possibly sparking evaluation of sub-components of \( a \) in parallel),
  – and returns an equivalent \( a \) in the Eval monad

• NB. the return value should be observably equivalent to the original
  – (why not the same? we’ll come back to that...)
Example...

- A **Strategy** on lists that sparks each element of the list
- This is usually not sufficient – suppose we want to evaluate the elements fully (e.g. with **force**), or do **parList** on nested lists.
- So we parameterise **parList** over the **Strategy** to apply to the elements:

```haskell
parList :: Strategy [a] => Strategy a -> Strategy [a]
```
• This is what we mean by “composable”:
  – given a Strategy on the list elements,
  – `parList` gives us a Strategy on lists of those elements

• We have some simple Strategies already:

```haskell
parList :: Strategy a -> Strategy [a]

type Strategy a = a -> Eval a

rpar :: a -> Eval a  -- same as Strategy a
rseq :: a -> Eval a  -- ditto

r0 :: Strategy a
rdeepseq :: NFData a -> Strategy a

so here’s a simple composition:

parList rdeepseq :: Strategy [a]
```
Strategies are easy to define

- We have the building blocks:

```haskell
type Strategy a = a -> Eval a
parList :: Strategy a -> Strategy [a]

rpar :: a -> Eval a

parList :: (a -> Eval a) -> [a] -> Eval [a]
  -- same as Strategy a -> Strategy [a]

parList s [] = return []
parList s (x:xs) = do
  x' <- rpar (runEval (s x))
  xs' <- parList s xs
  return (x':xs')
```
Let’s generalise...

- **parList** has **rpar** built-in, but we might not want that. Let’s make a version without the **rpar**:

```haskell
evalList :: (a -> Eval a) -> [a] -> Eval [a]
evalList f [] = return ()
evalList f (x:xs) = do
  x' <- f x
  xs' <- evalList f xs
  return (x':xs')
```

now we can define **parList** in terms of **evalList**:

```haskell
parList f = evalList (rparWith f)
```

```haskell
rparWith :: Strategy a -> Strategy a
rparWith s a = rpar (runEval (s a))
```
Let’s make a general **Strategy** on pairs:

```haskell
evalTuple2 :: Strategy a -> Strategy b -> Strategy (a, b)
evalTuple2 sa sb (a, b) = do
    a' <- sa a
    b' <- sb b
    return (a', b')
```

Example: a **Strategy** on a pair that evaluates the first component and sparks the second:

```haskell
evalTuple2 rseq rpar :: Strategy (a, b)
```

(left-then-right ordering is built into **evalTuple2**, if you want the other ordering you have to define a different **evalTuple2**)
Here are some example Strategies. What do they do?

```haskell
evalList (evalTuple2 rpar r0) :: Strategy [(a, b)]

evalList (rparWith (evalTuple2 rseq rseq)) :: Strategy [(a, b)]

evalList (evalTuple2 rdeepseq rpar) :: Strategy [(a, b)]

evalList (evalList rpar) :: Strategy [[a]]

evalList (rparWith (evalList rseq)) :: Strategy [[a]]

evalList (rparWith (evalList rpar)) :: Strategy [[a]]
```
How do we *use* a Strategy?

- We could just use `runEval`
- But this is better:
  \[
  x \ `using` \ s = runEval \ (s \ x)
  \]
- e.g.
  ```haskell
  myList `using` parList rdeepseq
  ```
- Why better? Because we have a “law”:
  - \[ x `using` s \approx x \]
  - We can insert or delete “`using` s” without changing the semantics of the program
Is that really true?

1. It relies on a **Strategy** returning “the same value” (*identity-safety*)
   - Strategies from the library obey this property
   - Be careful when writing your own Strategies

2. `x `using` s` might do more evaluation than just `x`.
   - So the program with `x `using` s` might be `_|_`, but the program with just `x` might have a value

- if identity-safety holds, adding **using** cannot make the program produce a different result (other than `_|_`)
But we wanted \texttt{parMap}

- Earlier we used \texttt{parMap} to parallelise Sudoku
- But \texttt{parMap} is a combination of two concepts:
  - The \textit{algorithm}, ‘map’
  - The \textit{parallelism}, ‘parList’

\[
\text{parMap } f\ x = \text{map } f\ xs \text{ `using` parList } rseq
\]

- With Strategies, the algorithm can be separated from the parallelism.
  - The algorithm produces a (lazy) result
  - A \textbf{Strategy} filters the result, but does not do any computation – it returns the same result.
• So a nicer way to write the Sudoku example is:

```haskell
main :: IO ()
main = do
    [f] <- getArgs
    grids <- fmap lines $ readFile f
    evaluate (length grids)
    evaluate $ force $ map solve grids `using` parList rseq
```

• Here the parallelism is modular
Recap...

- Eval monad, for expressing evaluation order and sparking:
  ```haskell
data Eval a -- instance Monad Eval
runEval :: Eval a -> a
rpar :: a -> Eval a
rseq :: a -> Eval a
```

- Strategies,
  - built using Eval, rpar, rseq
  - express compositional parallelism over data structures
  - modular: parallelism separate from algorithm

```haskell
type Strategy a = a -> Eval a
using :: a -> Strategy a -> a
```