Weekly Status Report 2009.03.11

Group One.
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Project: Smooth walker.
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Done this Week

We used a Graphical Modeling Tool called Medit to designed a gait for AIBO, and implemented the simple gait using the OPEN-R code.
This is only a tryout. We were trying to let it stand then move towards. On the really robot, it stood up then the legs moved without body moving.
The problems are because the gait designing and the angle setting of the joints is not reasonable.
We found out not only the gait itself, the legs' joint angle setting also produce a lot of shaking.

To do in the next Week

In the coming week, we will continue trying out some code about gait.
We will research the two points, the gait design and joints angle setting, and try to give a solution based on the researching.