Weekly Status Report 2009.03.24

Group One.
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Project: Smooth walker.
Date: 2009.03.24

Done this week.

● We implemented a Java-client for sending requests to the robot, let W3AIBO object take
  JPEG pictures through the head camera and then send back to the PC. The Java client sent
  requests periodically, and it saved pictures into the disk.
● We did some researches about how to read images into Matlab, and how to analyze these
  pictures using Matlab.

To do in the next Week

● The gait we designed last week was obviously not stable enough, we should try to minimize the
  shaking by modifying the joints angle.
● Modify the code to support receiving commands from the web-console, research on the
  MotionCommander sample might be usefull.