Uppsala University Dept. of Systems and Control

Final Exam in System Identification for F4

Answers and brief solutions

Date: March 14, 2008 Examiner: Magnus Mossberg

1.

$$\begin{bmatrix} \sum i^2(t-1) & -\sum i(t-1)u(t-1) \\ -\sum i(t-1)u(t-1) & \sum u^2(t-1) \end{bmatrix} \begin{bmatrix} \hat{a} \\ \hat{b} \end{bmatrix} = \begin{bmatrix} -\sum i(t)i(t-1) \\ \sum i(t)u(t-1) \end{bmatrix}$$

2. a)

$$\begin{aligned} r_{yu}(\tau) &= \mathrm{E}\{y(t+\tau)u(t)\} \\ &= \mathrm{E}\left\{\left(\sum_{k=0}^{\infty} g(k)u(t+\tau-k)+v(t)\right)u(t)\right\} \\ &= \mathrm{E}\left\{\sum_{k=0}^{\infty} g(k)u(t+\tau-k)u(t)\right\} \\ &= \sum_{k=0}^{\infty} g(k)r_u(\tau-k) \\ &= g(k)\delta_{\tau,k}\lambda^2 \\ &= \lambda^2 g(\tau) \end{aligned}$$

b)

$$\hat{r}_{yu}(\tau) = \frac{1}{N} \sum_{t=1-\min(\tau,0)}^{N-\max(\tau,0)} y(t+\tau)u(t), \quad \tau = 0, \pm 1, \pm 2, \dots$$

which gives

$$\hat{g}(\tau) = \frac{1}{\hat{\lambda}^2} \hat{r}_{yu}(\tau)$$

where $\hat{\lambda}^2$ is an estimate of λ^2 .

3. a)

$$\begin{split} \hat{a} &= \left(\frac{1}{N}\sum_{t=1}^{N}\varphi^2(t)\right)^{-1} \left(\frac{1}{N}\sum_{t=1}^{N}\varphi(t)y(t)\right) \\ &= \left(\frac{1}{N}\sum_{t=1}^{N}y^2(t-1)\right)^{-1} \left(-\frac{1}{N}\sum_{t=1}^{N}y(t-1)y(t)\right) \\ &\xrightarrow[N \to \infty]{} - \frac{r_y(1)}{r_y(0)} = a_0 \end{split}$$

b)

$$\operatorname{var}(\hat{a}) \approx \frac{\lambda^2}{N} \bar{R}^{-1}$$

where

$$\bar{R} = \mathrm{E}\{\varphi^2(t)\} = r_y(0) = \frac{\lambda^2}{1 - a_0^2}$$

 \mathbf{so}

$$\operatorname{var}(\hat{a}) \approx \frac{1 - a_0^2}{N}$$

4.

$$\hat{c}(t) = \left(\sum_{k=1}^{t} 0.9^{t-k}\right)^{-1} \sum_{k=1}^{t} 0.9^{t-k} y(k)$$
$$\hat{c}(t) = \hat{c}(t-1) + \frac{0.1}{1-0.9^t} \left(y(t) - \hat{c}(t-1)\right)$$

5. A discussion can be made based on the material in the course book.

6. a)

$$\mathbf{E}\{\hat{c}\} = \frac{1}{2}c$$

b)

$$\operatorname{var}(\hat{c}) = \frac{\sigma^2}{4N}$$

7. a)

$$\mathbf{E}\{z(t)\varphi^{T}(t)\} = \begin{bmatrix} b_{0}\lambda^{2} & kb_{0}\lambda^{2} \\ 0 & \lambda^{2} \end{bmatrix}$$

b) Choose u(t) so that it is sufficiently variational, persistently exciting of sufficient order, and so that $\frac{1}{N} \sum_{t=1}^{N} \varphi(t) \varphi^{T}(t)$ is invertible.