

Background Model Algorithm Conclusion

Context

- Reactive System**
 - Never terminates
 - Input & output during execution
- Program Verification**
 - Communication protocols
 - Hardware
- One approach to verification:**
- Model checking**
 - Input: model + formula
 - Output: "yes, formula true" / "no, formula false"

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Background Model Algorithm Conclusion

Reachability

- F – set of “target states”
- F reached?

Example:

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Background Model Algorithm Conclusion

Game Probabilistic Lossy Channel Systems (GPLCS)

- Game:** Interaction with evil cracker
- Probabilistic:** Messages lost randomly (probability λ)

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Background Model Algorithm Conclusion

Overview

- Background**
- Model**
- Algorithm**
- Conclusion**

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Background Model Algorithm Conclusion

Stochastic Infinite-State Games

- Stochastic**
 - Unreliable communication
 - Fault-Tolerant systems
 - Randomized algorithms
- Infinite-State**
 - Unbounded queues, stacks, counters, ...
 - Time
 - Unbounded parallelism
- Games**
 - Model interacts with environment
 - Abstraction in logics
 - Abstraction

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Background Model Algorithm Conclusion

Lossy Channel Systems (LCS)

- Model:**
 - Finite state processes
 - Unbounded lossy channels
 - Send & receive operations
- Motivation:**
 - Models of communication protocols

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Background Model Algorithm Conclusion

Overview

- Background**
- Model**
- Algorithm**
- Conclusion**

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Background Model Algorithm Conclusion

Stochastic Infinite-State Games

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Background Model Algorithm Conclusion

Overview

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Background Model Algorithm Conclusion

Repeated Reachability

- F – set of “target states”
- F reached infinitely often?

Example:

- Will it always return to the green state?

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Background Model Algorithm Conclusion

Repeated Reachability

- F – set of “target states”
- F reached infinitely often?

Example:

- Will it always return to the green state?

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Background Model Algorithm Conclusion
Game Probabilistic Lossy Channel Systems (GPLCS)

Transitions:

Send: $\text{!}m$ Receive: $\text{?}n$

Send: $m \text{ p } p \text{ m } \dots$ Receive: $\text{!}m \text{ p } p \text{ m } \dots$

Background Model Algorithm Conclusion
Stochastic Games

- Every GPLCS induces a stochastic game
- 3 types of states:
 - Player GOOD (blue circle)
 - Player BAD (red circle)
 - Player RANDOM (yellow diamond)

Background Model Algorithm Conclusion
Game Probabilistic Lossy Channel Systems (GPLCS)

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Background Model Algorithm Conclusion
Repeated Reachability for GPLCS

- **Input:**
 - GPLCS
 - Set F of final states
- **Output: Partition of states:**
 - Winning for GOOD
 - Bad forces $\text{Pro}(\text{reach } F \text{ init, often}) < 1$
 - Good forces $\text{Pro}(\text{reach } F \text{ init, often}) = 1$

Background Model Algorithm Conclusion
Overview

- Background
- Models
- **Algorithm**
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Background Model Algorithm Conclusion
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Background Model Algorithm Conclusion
Overview

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- Models
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- Conclusion

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Background Model Algorithm Conclusion
Game Probabilistic Lossy Channel Systems (GPLCS)

Sufficient:

- One channel
- One process
- Each state controlled by a player

Properties:

- Infinite state space
- Perfect channel = Turing machine

Background Model Algorithm Conclusion
Stochastic Games

- Probabilistic message loss:

$p \text{ m } n \text{ p } n \dots$ \downarrow $p \text{ n } n \text{ p } \dots$

- Each transition: each message lost with prob $A > 0$, independently

Background Model Algorithm Conclusion
Game Probabilistic Lossy Channel Systems (GPLCS)

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Background Model Algorithm Conclusion
Repeated Reachability for GPLCS

- **Strategy** = selection of outgoing transitions
- **Strategies for GOOD & BAD**
 - Only probabilistic choices remain
 - "Prob(event)" well-defined

Background Model Algorithm Conclusion
Stochastic Games

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Background Model Algorithm Conclusion
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Repeated Reachability for GPLCS

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Background Model Algorithm Conclusion
Stochastic Games

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Background **Model** **Algorithm** **Conclusion**

Subroutine: Force-set Construction

- Force-set \approx "Reachability for games"
 - Given target set Q
 - Compute the set of states where **Good** can force Prob(reach $Q) > 0$
- Backward search

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Background **Model** **Algorithm** **Conclusion**

Subroutine: Force-set Construction

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Background **Model** **Algorithm** **Conclusion**

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Background **Model** **Algorithm** **Conclusion**

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 - Given target set Q
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Background **Model** **Algorithm** **Conclusion**

Subroutine: Force-set Construction

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 - Given target set Q
 - Compute the set of states where **Good** can force Prob(reach $Q) > 0$
- Backward search

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Background **Model** **Algorithm** **Conclusion**

Subroutine: Force-set Convergence

- Force-set \approx "Games"
 - Given target set Q
 - Compute the set of states where **Good** can force Prob(reach $Q) > 0$
- Backward search

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Background **Model** **Algorithm** **Conclusion**

Subroutine: Force-set Construction

- Force-set \approx "Reachability for games"
 - Given target set Q
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Background **Model** **Algorithm** **Conclusion**

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Background **Model** **Algorithm** **Conclusion**

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Background Model Algorithm Conclusion

Algorithm Idea

- A world of islands and water
- No food (= F) on islands
- In water, may float to island (possibly elsewhere, too)
- Find **BAD** Islands and water!

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Background Model Algorithm Conclusion

Algorithm Idea

- A world of islands and water
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Background Model Algorithm Conclusion

Algorithm Idea

- A world of islands and water
- No food (= F) on islands
- In water, may float to island (possibly elsewhere, too)
- Find **BAD** Islands and water!

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Background Model Algorithm Conclusion

Subroutine: Force-set Correctness

- Force-set** "times"
 - Given target
 - Compute the set of states where Good can force $\exists Q_n . \text{Good can force Prob(reach } Q) > 0 \text{ by construction}$

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Background Model Algorithm Conclusion

Algorithm Idea

- A world of islands and water
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Background Model Algorithm Conclusion

Algorithm Idea

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Background Model Algorithm Conclusion

Subroutine: Force-set Correctness

- Force-set** "times"
 - Given target
 - Compute the set of states where Good can force $\exists Q_n . \text{Good can force Prob(reach } Q) > 0 \text{ by construction}$
 - Backward search**

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Background Model Algorithm Conclusion

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Background Model Algorithm Conclusion

Algorithm Idea

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- In water, may float to island (possibly elsewhere, too)
- Find **BAD** Islands and water!

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Background Model Algorithm Conclusion

Subroutine: Force-set Correctness

- Force-set** "times"
 - Given target
 - Compute the set of states where Good can force $\exists Q_n . \text{Good can force Prob(reach } Q) > 0 \text{ by construction}$
 - Backward search**
 - YES!** (and I'll show why)

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Background Model Algorithm Conclusion

Algorithm Idea

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- No food (= F) on islands
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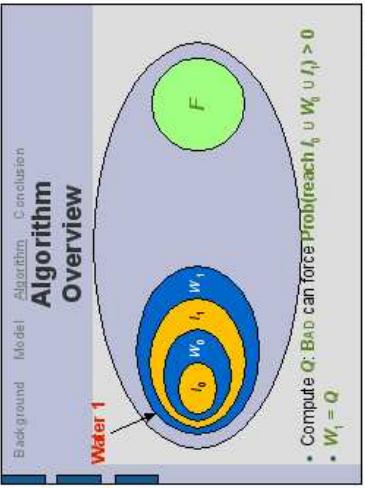
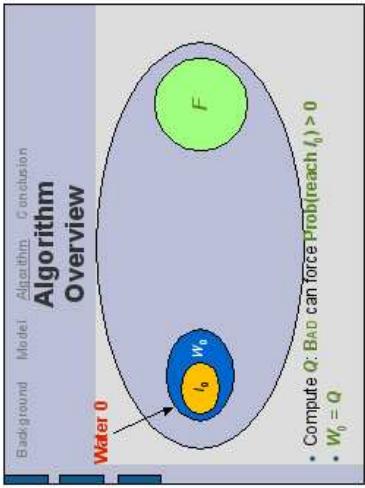
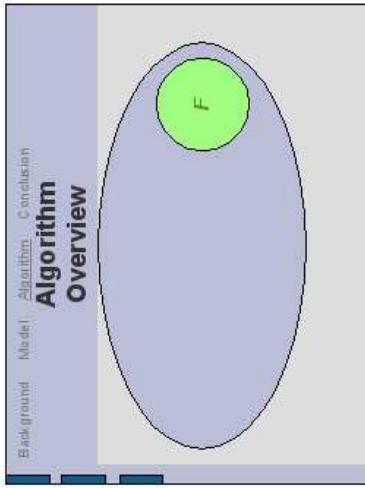
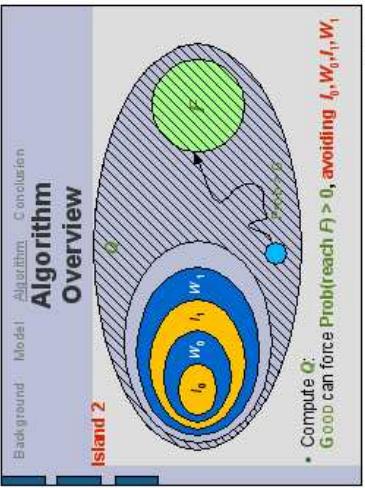
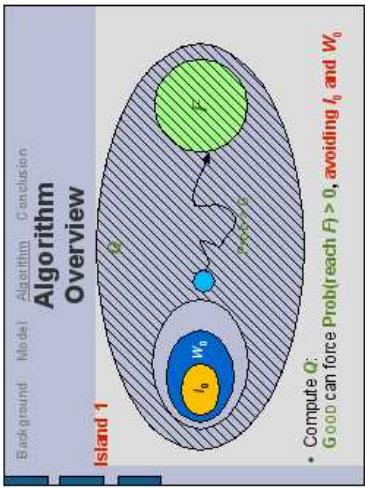
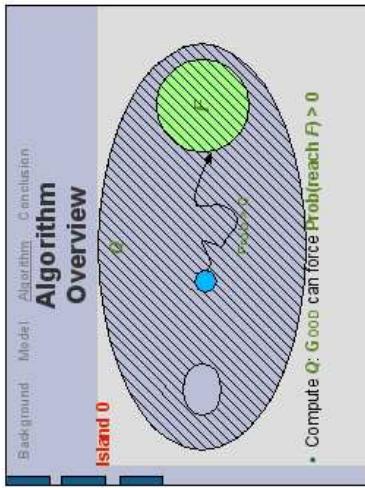
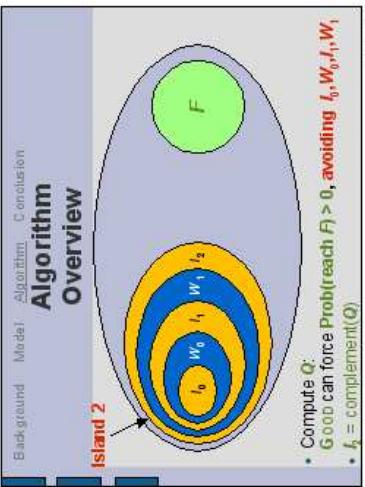
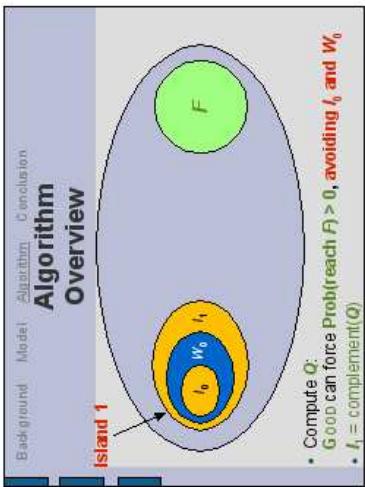
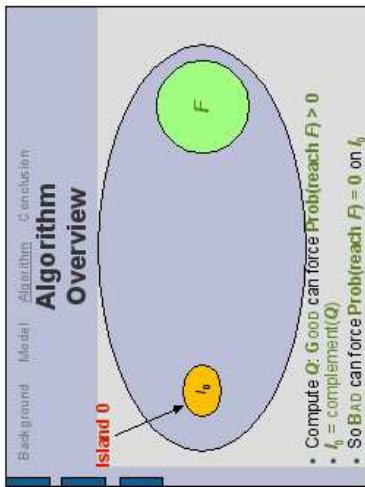
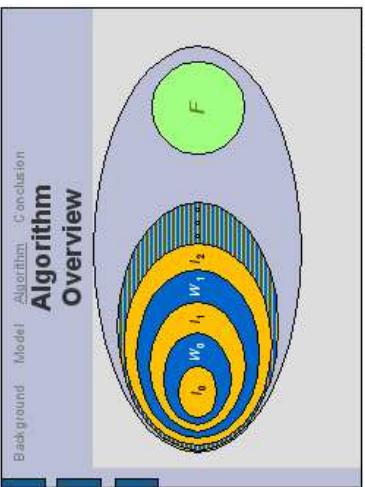
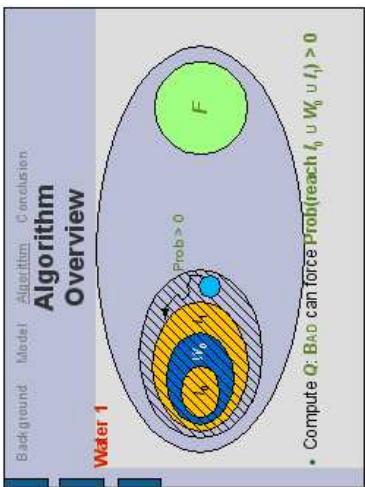
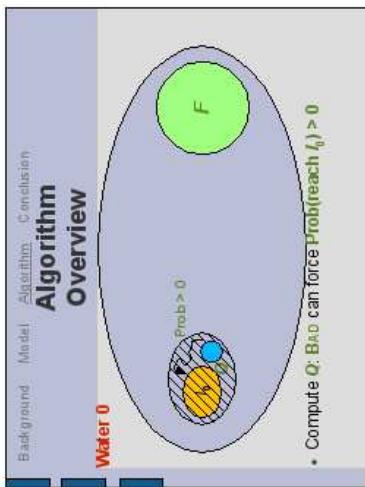
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- Find **BAD** Islands and water!

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Background Model Algorithm Conclusion
Algorithm Correctness

Correct?
YES! (and I'll show why)

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Background Model Algorithm Conclusion
Algorithm Correctness

Correct?
Bad can force
Prob(reach F, inf. often) < 1
In W_2: Prob(reach F, inf. often) < 1 (since Prob(reach l_2) > 0)

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Background Model Algorithm Conclusion
Algorithm Correctness

Correct?
Good can force
Prob(reach F, inf. often) = 1
In l_2: Prob(reach F, inf. often) < 1 (since even Prob(reach F) = 0)

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Background Model Algorithm Conclusion
Algorithm Correctness

Correct?

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Background Model Algorithm Conclusion
Algorithm Correctness

Correct?
Bad can force
Prob(reach F, inf. often) < 1
In l_2: Prob(reach F, inf. often) < 1 (since even Prob(reach F) = 0)

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Background Model Algorithm Conclusion
Algorithm Correctness

Correct?
Good can force
Prob(reach F, inf. often) = 1
In l_2: Prob(reach F, inf. often) < 1 (since even Prob(reach F) = 0)

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Background Model Algorithm Conclusion
Algorithm Convergence

Converges?
YES! for GPLCS (well quasi orders, difficult)

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Background Model Algorithm Conclusion
Algorithm Correctness

Correct?
Bad can force
Prob(reach F, inf. often) < 1
In l_2: Prob(reach F, inf. often) < 1 (since even Prob(reach F) = 0)

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Background Model Algorithm Conclusion
Algorithm Correctness

Correct?
Good can force
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In l_2: Prob(reach F, inf. often) < 1 (since even Prob(reach F) = 0)

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Background Model Algorithm Conclusion
Algorithm Convergence

Converges?

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Background Model Algorithm Conclusion
Algorithm Correctness

Correct?
Bad can force
Prob(reach F, inf. often) < 1
In l_2: Prob(reach F, inf. often) < 1 (since even Prob(reach F) = 0)

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Background Model Algorithm Conclusion
Algorithm Correctness

Correct?
Good chooses how to die:
• stay in l_n and lose (no F)
• or go to W_{n-1} and lose
In l_n: Prob(reach F, inf. often) < 1 (since even Prob(reach F) = 0)

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Background Model Algorithm Conclusion

Algorithm Correctness

Good can force
Prob(reach F | inf, often) = 1

Correct?

So Good can force:
Always Prob(reach F) > 0

For GPLCS, this implies
Convergence (Using attractors, difficult)

• Convergence means:
- No more water \Rightarrow Good can stay outside I_n, W_n
- No more island \Rightarrow Good can force Prob(reach F) > 0

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Background Model Algorithm Conclusion

Extensions

Good can force
Prob(reach F | inf, often) = 1

Correct?

So Good can force:
Always Prob(reach F) > 0

For GPLCS, this implies
Convergence (Using attractors, difficult)

• Construct winning strategies
• Concurrent games
• Simultaneous moves
• Reachability games
Can Good force Prob(reach F) = 1?
• Parity games
Generalization of repeated reachability
Unclear

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Background Model Algorithm Conclusion

Convergence: Well Quasi Orders

Good can force
Prob(reach F | inf, often) = 1

Correct?

So Good can force:
Always Prob(reach F) > 0

For GPLCS, this implies
Convergence (Using attractors, difficult)

If we can lose some messages...
...then we can lose more!

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Background Model Algorithm Conclusion

Algorithm Correctness

Good can force
Prob(reach F | inf, often) = 1

Correct?

So Good can force:
Always Prob(reach F) > 0

• Convergence means:
- No more water \Rightarrow Good can stay outside I_n, W_n
- No more island \Rightarrow Good can force Prob(reach F) > 0

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Background Model Algorithm Conclusion

Algorithm

Good can force
Prob(reach F | inf, often) = 1

Correct?

So Good can force:
Always Prob(reach F) > 0

• Force-set:
- Prob(reach Q) > 0
- Backward search

• Winning sets for BAD:
- Prob(reach F | inf, often) < 1
- Search for islands and water

• ...

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Background Model Algorithm Conclusion

Convergence: Well Quasi Orders

Good can force
Prob(reach F | inf, often) = 1

Correct?

So Good can force:
Always Prob(reach F) > 0

If we can lose some messages...
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Background Model Algorithm Conclusion

Algorithm Correctness

Good can force
Prob(reach F | inf, often) = 1

Correct?

So Good can force:
Always Prob(reach F) > 0

• Convergence means:
- No more water \Rightarrow Good can stay outside I_n, W_n
- No more island

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Background Model Algorithm Conclusion

The Problem We Studied

Good can force
Prob(reach F | inf, often) = 1

Correct?

So Good can force:
Always Prob(reach F) > 0

• GPLCS:
Protocol vs. Cracker

• Repeated reachability:
reach "good" state infinitely many times

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Background Model Algorithm Conclusion

Convergence: Well Quasi Orders

Good can force
Prob(reach F | inf, often) = 1

Correct?

So Good can force:
Always Prob(reach F) > 0

• Recall: State: $s = (\Delta, \text{mp})$

• Subword ordering:
 $\text{mp} \sqsubseteq \text{mpmp}$

• Upward closure:
all "bigger" states

• Message loss
 \Rightarrow subword

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Background Model Algorithm Conclusion

Algorithm Correctness

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Prob(reach F | inf, often) = 1

Correct?

So Good can force:
Always Prob(reach F) > 0

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Background Model Algorithm Conclusion

Overview

Good can force
Prob(reach F | inf, often) = 1

Correct?

So Good can force:
Always Prob(reach F) > 0

• Background

• Models

• Algorithm

• Conclusion

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Background Model Algorithm Conclusion

The End

Good can force
Prob(reach F | inf, often) = 1

Correct?

So Good can force:
Always Prob(reach F) > 0

Questions?

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Background Model Algorithm Conclusion Bonus Slide

Convergence of Force-sets: Well Quasi Orders

- Theorem (Higman 1952):**
Any sequence of increasing, upward closed sets converges.
- Upward closed terminates!**
- Every 2nd step is a loss
⇒ terminates!**

Player states Random states

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Background Model Algorithm Conclusion Bonus Slide

Leftover

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Background Model Algorithm Conclusion Bonus Slide

Convergence of Force-sets: Well Quasi Orders

- Theorem (Higman 1952):**
Any sequence of increasing, upward closed sets converges.
- We apply it:**
- Upward closed terminates!**

Player states Random states

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Background Model Algorithm Conclusion Bonus Slide

Leftover

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Background Model Algorithm Conclusion Bonus Slide

Convergence of Force-sets: Well Quasi Orders

- If we can lose some messages...**
- ...then we can lose more!**
- We apply it:**
- Upward closed terminates!**

Conclusion: RANDOM states one step before are upward closed

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Background Model Algorithm Conclusion Bonus Slide

The Fine Print: Finite-Memory Strategies

- We assume BAO is restricted to finite-memory strategies**
- BAO cannot remember unbounded amount of history**
- Intuition:** Evil cracker has a finite hard disk
- Needed to prove correctness**

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Background Model Algorithm Conclusion Bonus Slide

Convergence of Algorithms: Well Quasi Orders

- Argument is much more difficult!**
- RANDOM states in water upward closed**
- Sequence of waters terminates**
- Sequence of islands terminates**

Player states Random states

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Background Model Algorithm Conclusion Bonus Slide

Repeated Reachability

- F – set of “target states”**
- Is F reached infinitely often?**

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Background Model Algorithm Conclusion Bonus Slide

- Example:**
 - Will it always return to the green state?

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