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Physics-informed machine learning

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Division of System and Control
Department of Information Technology

Joint work with

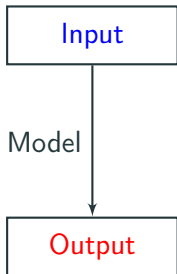
Carl Jidling, **Thomas Schön**, (Uppsala University), **Adrian Wills**, **Johannes Hendriks**,
Alexander Gregg, **Chris Wensrich** (University of Newcastle, Australia), **Arno Solin**,
Simo Särkkä (Aalto University), **Manon Kok** (Delft University of Technology), **Roland**
Hostettler (Uppsala University), **Fredrik Gustafsson** (Linköping University)

Celsius-Linnaeus Lecturers with Symposium
February 11, 2021.

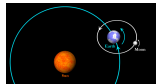
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Example A: *Predicting next solar eclipse*



*Present position
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*Next total solar
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2126)*



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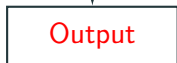
Example B: *Image classification*



An image



Model



What the image depicts

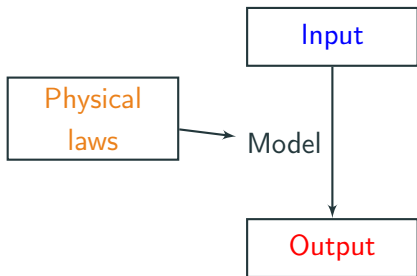
A church

How do we find models?

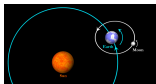
Finding models

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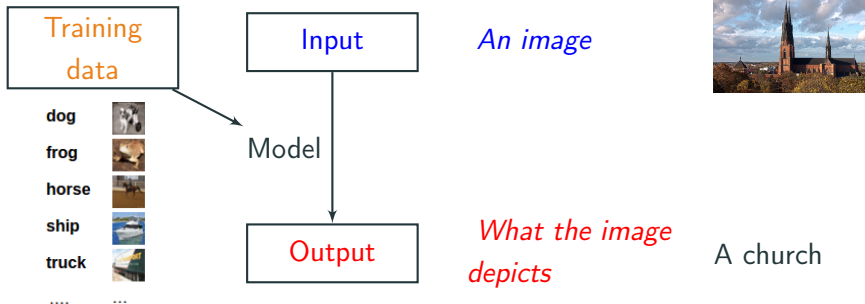
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Finding models

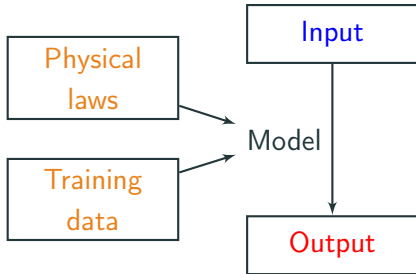
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Example B: *Image classification*



Physics-informed machine learning

In **physics-based machine learning** we make use first principles to leverage the performance of data-driven machine learning models.



Physics-informed machine learning

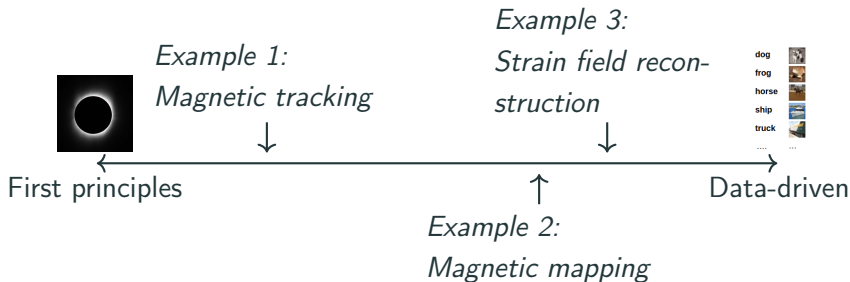
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Finding models that can make use for both first principles and data-driven approaches is an active research field

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Advantages with magnetometers

- Cheap sensors



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- Low energy consumption



Magnetometer measurement models

1. **Common use:** Magnetometer provides **orientation** heading information.

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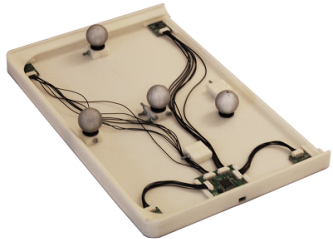
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Example 1: Magnetic tracking

Problem setup

We have:

- A sensor network of magnetometers
- A moving magnetic object in the vicinity of that network

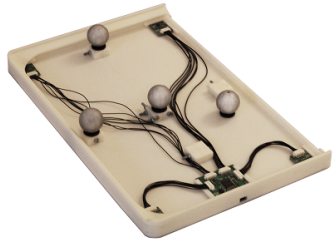


Example 1: Magnetic tracking

Problem setup

We have:

- A sensor network of magnetometers
- A moving magnetic object in the vicinity of that network



What we want to know: The position and orientation of the magnetic object

What we observe: The magnetic field measured by the magnetometers

Physical laws: The magnetic dipole model

Example 1: Magnetic tracking

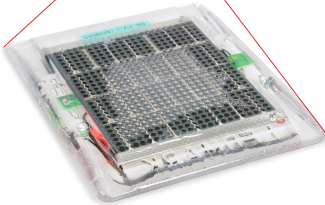
Interactive 3D-modelling

Example 1: Magnetic tracking

Traffic surveillance

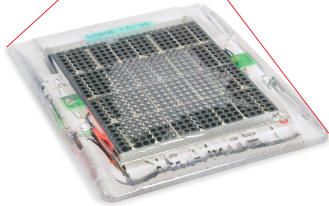
Traffic surveillance with wireless sensors

- Each unit is equipped with a magnetometer



Example 1: Magnetic tracking

Traffic surveillance



Traffic surveillance with wireless sensors

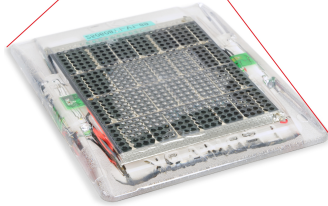
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Limitations:

- Powered by solar cells
- Small computational budget

Example 1: Magnetic tracking

Traffic surveillance



Traffic surveillance with wireless sensors

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Information that can be retrieved

- Count number of cars
- Type of car
- Driving direction

Magnetometer measurement models

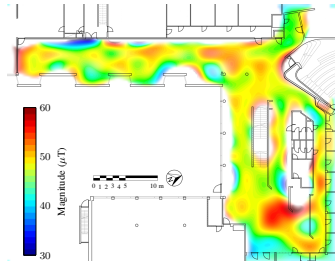
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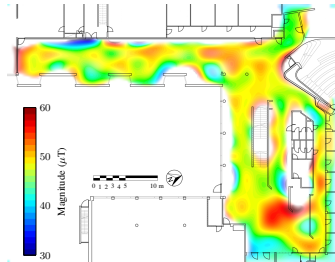
Example 2: Magnetic mapping - Build magnetic maps

- The magnetic field changes due to metal structures in the buildings.
- These changes can be used as a map!



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What we want to know: The magnetic field

Training data: The magnetic field at a few places

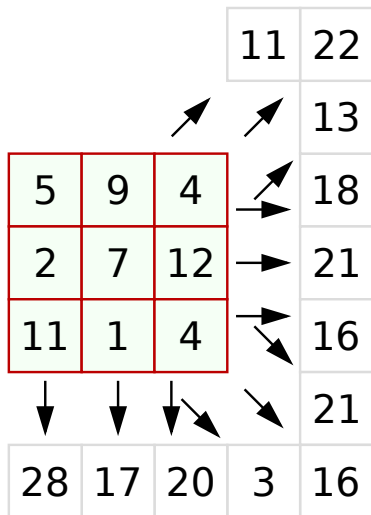
Physical laws: The magnetic field must satisfy Maxwell's equations

Example 2: Magnetic mapping - Build magnetic maps

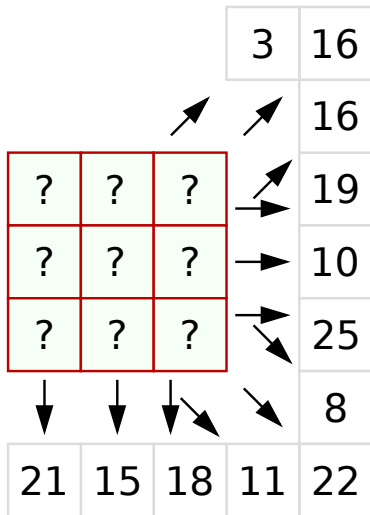
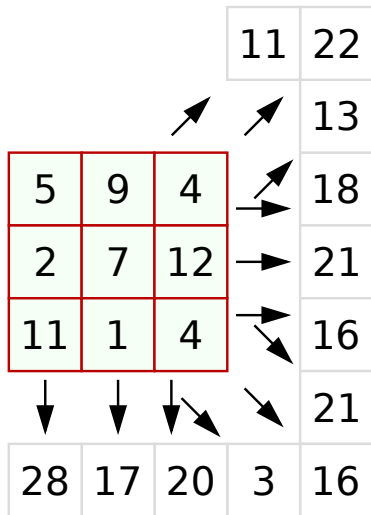
Arno Solin, Manon Kok, Niklas Wahlström, Thomas B. Schön and Simo Särkkä, Modeling and interpolation of the ambient magnetic field by Gaussian processes *IEEE Transactions on Robotics*, 34(4):1112 – 1127, 2018

Example 3: Strain field reconstruction - intuition

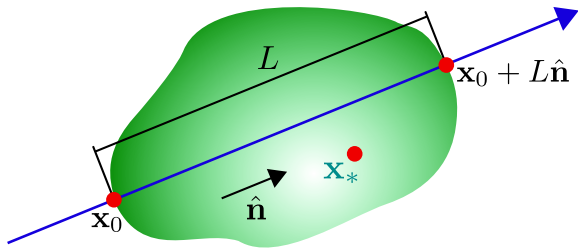
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Example 3: Strain field reconstruction – problem setup



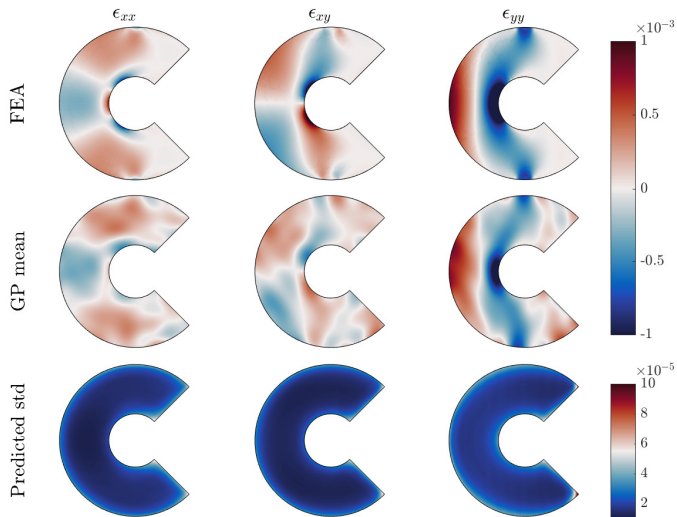
What we want to know: The strain field

Training data: Neutron beams through the object in various directions

Physical laws: A physical strain field must satisfy the *equilibrium constraints*

$$\begin{aligned} 0 &= \frac{\partial f_{xx}(\vec{x})}{\partial x} + (1 - \nu) \frac{\partial f_{xy}(\vec{x})}{\partial y} + \nu \frac{\partial f_{yy}(\vec{x})}{\partial x} \\ 0 &= \nu \frac{\partial f_{xx}(\vec{x})}{\partial y} + (1 - \nu) \frac{\partial f_{xy}(\vec{x})}{\partial x} + \frac{\partial f_{yy}(\vec{x})}{\partial y} \end{aligned}$$

Example 3: Strain field reconstruction – experimental results



Carl Jidling, Johannes Hendriks, Niklas Wahlström, Alexander Gregg, Thomas B. Schön, Chris Wensrich, Adrian Wills. Probabilistic modelling and reconstruction of strain, *Nuclear instruments and methods in physics research section B*, 436:141-155, 2018.

Summary

In **physics-based machine learning** we make use first principles to leverage the performance of data-driven machine learning models.

I have presented three examples from our research which exemplify this

